

CS 512, Spring 2017, Handout 31
SMT Solver = SAT Solver + a theory
(continuation of *Handout 12: SAT Solvers*)

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PRELIMINARIES

- ▶ SMT = *Satisfiability Modulo a Theory*.
- ▶ Theory = *the quantifier-free fragment of a first-order theory*.¹
- ▶ SMT Solver = *SAT solver* working with a *theory solver* (or *T-solver*).

¹See Handout 18 for details on first-order theories.

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- ▶ Examples of first-order theories considered in SMT solvers, in each case limited to the *quantifier-free fragment*:
 - ▶ Equality with Uninterpreted Functions (EUF) – Handout 18, pp 3-4
 - ▶ Linear Integer Arithmetic (LIA) – Handout 18, p 21
 - ▶ Linear Real Arithmetic (LRA) – similar to LIA, except that the domain is \mathbb{Q} (set of rationals) or \mathbb{R} (set of reals).
 - ▶ Difference Logic (DL), which is a fragment of LRA
 - ▶ other theories:
 - ▶ Arrays , Bit-Vectors , Tuples and Records , Algebraic Datatypes , etc.

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 - ▶ other theories:
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- ▶ Reason for the restriction to quantifier-free fragments:
Given a theory T , we need an efficient decision procedure to decide validity relative to T , i.e., to “quickly” decide whether $T \vdash \varphi$.

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Two General Approaches to SMT Solving

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- ▶ Lazy Methods

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▶ Lazy Methods

- ▶ Interleave SAT-solver steps with T-solver steps, but keep the two separate.
- ▶ More widely applicable than **eager methods**.
- ▶ Most common approach:
CDCL SAT-solver combined with a T-solver.²

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