

## CS480/CS680 Problem Set 1

Due in class Thursday, October 5 at the beginning of lecture.

Please prepare the answers to these questions, neatly written or typed, on separate paper.

1. (a) (3 points) Write a  $4 \times 4$  homogeneous transform matrix  $\mathbf{M}$  that when applied to a point  $(x, y, z, 1)$  yields  $(x', y', z', w')$  where

$$\begin{aligned}x' &= -2x \\y' &= -\frac{1}{\sqrt{2}}y - \frac{1}{\sqrt{2}}z + a \\z' &= \frac{1}{\sqrt{2}}z - \frac{1}{\sqrt{2}}y + a \\w' &= 1\end{aligned}$$

- (b) (12 points) In words, what four basic computer graphics transforms occur when we apply  $\mathbf{M}$  to a 3D point? Give a homogeneous transform matrix for each, and show the order in which they are multiplied.
2. (15 points) We have a unit cube centered at the point  $\mathbf{c} = (1.5, 0.5, 2.5)$ . Derive the homogeneous transformation matrix that will rotate the cube by angle  $\theta$  around a vector in the direction  $\mathbf{v} = (1, 0, 1)$ . The pivot point for the rotation is the cube's center  $\mathbf{c}$ .
3. Use quaternions in your answers to the following.
- (5 points) Prove that in general two 3D rotations about different rotation axes do not commute. You can assume that both rotation axes pass through the origin.
  - (15 points) Derive the general conditions under which 3D rotations commute.
4. (20 points) Problem 5-3 in the Hearn and Baker text. Give all steps in the derivation of your answer, as well as multiply out the final transformation matrix.
5. (30 points) In 2D we specify a line by the equation  $y = mx + b$ . Derive a homogenous transformation matrix that can be used to reflect 2D points about this line. Extend your result to reflection about a plane in three dimensions.
6. (CS680 only)
- We can specify a 3D affine transformation by considering the location of a small set of points both before and after the points have been transformed.
- (a) (5 points) What is the minimum number of points  $N$  needed to determine the transform uniquely? Be sure to give a mathematical justification for your answer.
- (b) (5 points) Are there any special conditions that these points must satisfy? Be sure to give a mathematical justification for your answer.
- (c) (15 points) Assume that we are given the point positions before transformation  $(\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_N)$  and their corresponding positions after the affine transformation  $(\mathbf{p}'_1, \mathbf{p}'_2, \dots, \mathbf{p}'_N)$ . Give the mathematical steps for estimating the affine transform given  $N$  points, where  $N$  is the minimum number required as determined in (a). Be sure to also include any mathematical steps for testing if the points satisfy the special conditions.