

CAS CS 585

Image and Video Computing

Lecture by Margrit Betke

Projections, Multi-object Labeling, and
Face Detection,

January 25, 2024

Last time: Geometric Properties of Object



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□ Representations of lines

□ Binary Image $B(x, y) = 1$ if $I(x, y) > \tau$,
 $= 0$ otherwise

□ Size, area: $A = \sum_{x=0}^{xdim-1} \sum_{y=0}^{ydim-1} B(x, y)$

$A =$ “0th moment”

□ Position: use 1st moment

□ Orientation: use 2nd moments

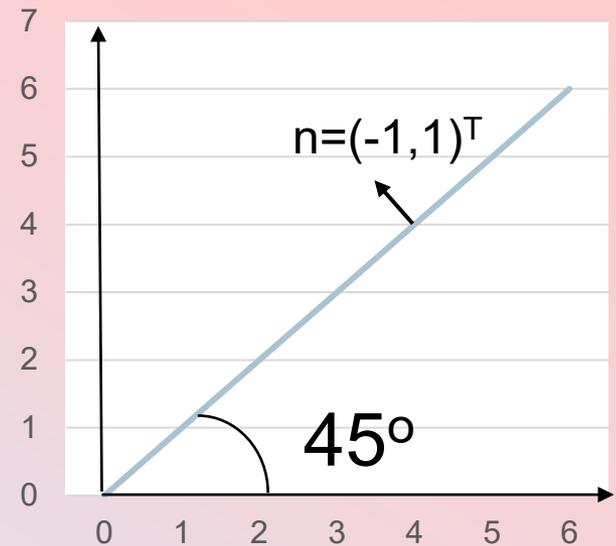
Class Poll:

Which line equation is wrong?

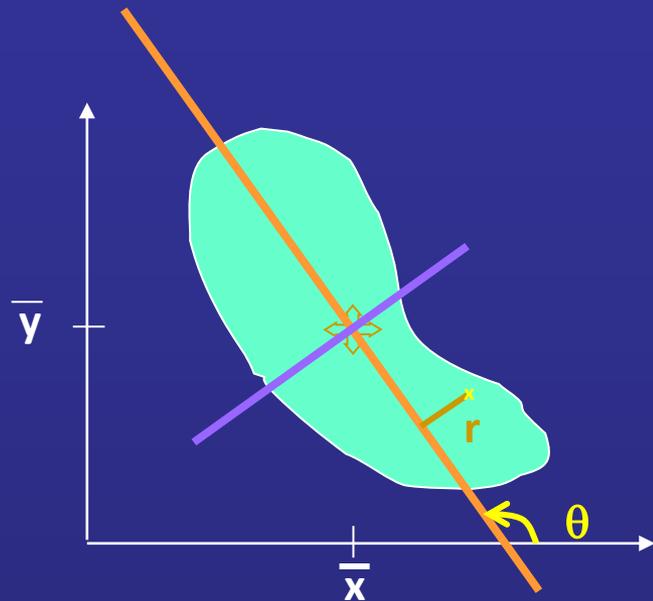


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- A. $y=mx+n$, where $m=1$, $n=0$
- B. $(-1,1)^T \mathbf{x} - g = 0$, where $g=\sqrt{2}$
- C. $-x \sin \alpha + y \cos \alpha = 0$, where $\alpha = 45$ degrees
- D. $(-\sin \pi/4, \cos \pi/4)^T \mathbf{x} = 0$



Object Shape: Round or Elongated?



Axis of least inertia =
Direction of elongation
 $\min E = \min \sum \sum r^2$

$a, b, c = 2^{\text{nd}}$ central moments

Circularity: $0 \leq E_{\min}/E_{\max} \leq 1$

$$E = \frac{1}{2}(a+c) - \frac{1}{2}(a-c)\cos 2\theta - \frac{1}{2}b\sin 2\theta$$

$$\sin 2\theta = \pm \frac{b}{\sqrt{b^2 + (a-c)^2}} \quad \cos 2\theta = \pm \frac{a-c}{\sqrt{b^2 + (a-c)^2}}$$

Example Application: American Sign Language Recognition



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Sign for A

Sign for B

Idea:

Distinguish the two signs by their size and circularity/elongation of hand.

Task: Object Localization



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Goal: Find an algorithm that draws a **bounding box** around the bat



Object Localization Algorithm: Conversion to Binary Image



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Color image



Greyscale image



Back-and-white image
= binary image:

Object Localization



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1. Find bounding box around black object in grayscale background

Background may contain black pixels



Algorithm ??

Using Black Color & Projections for Object Detection



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1. Find bounding box around black object in grayscale background

Background may contain black pixels



Algorithm:

- Count number of black pixels in each row and column
- Analyze these histograms or projections of black pixels onto x- and y-axes.

Using Black Color & Projections for Object Detection



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1. Find bounding box around black object in grayscale background

Background may contain black pixels



Algorithm:

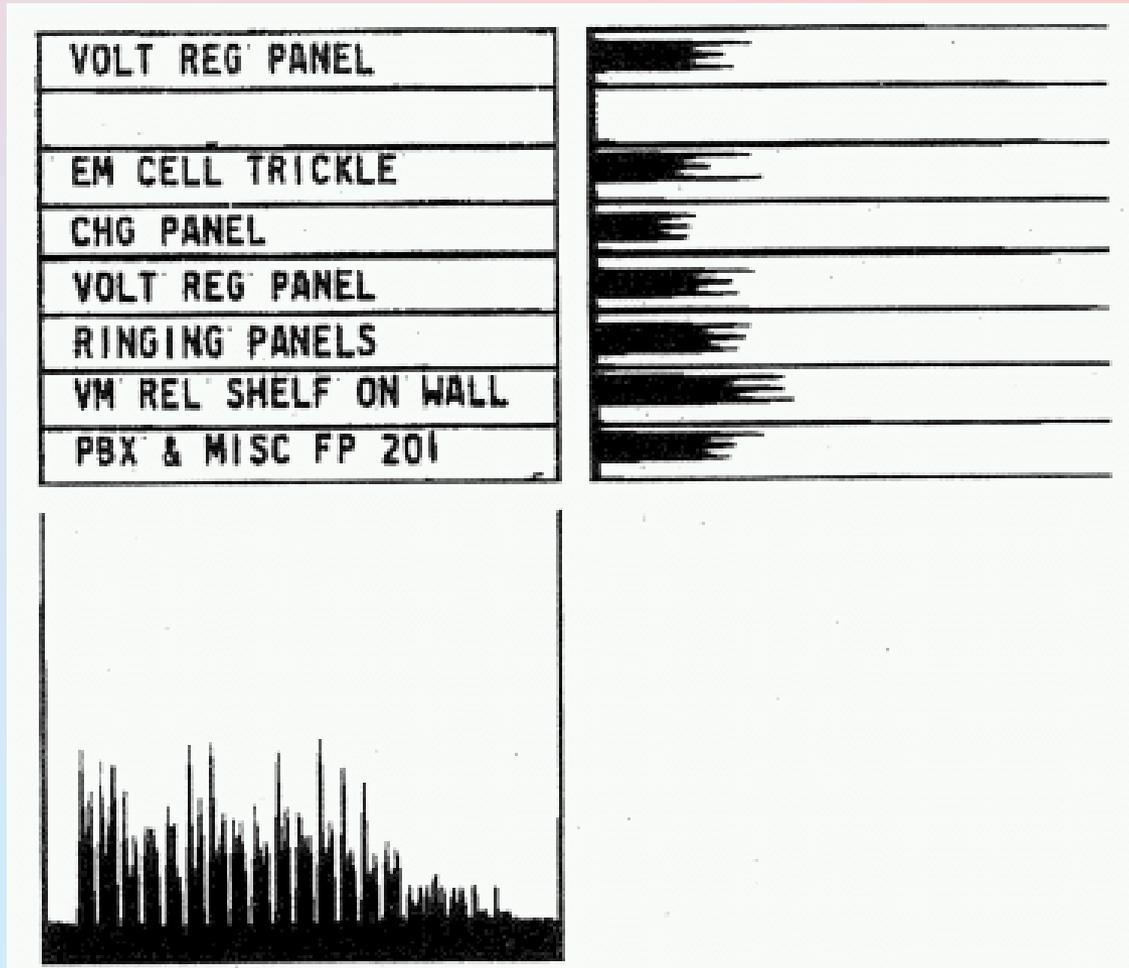
- Count number of black pixels in each row and column
- Analyze these histograms or projections of black pixels onto x- and y-axes.

$$P1(y) = \sum_x B(x,y), \quad P2(x) = \sum_y B(x,y)$$

Examples of Projections



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Examples of Projections



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String Quintet in B-flat Major, K.174

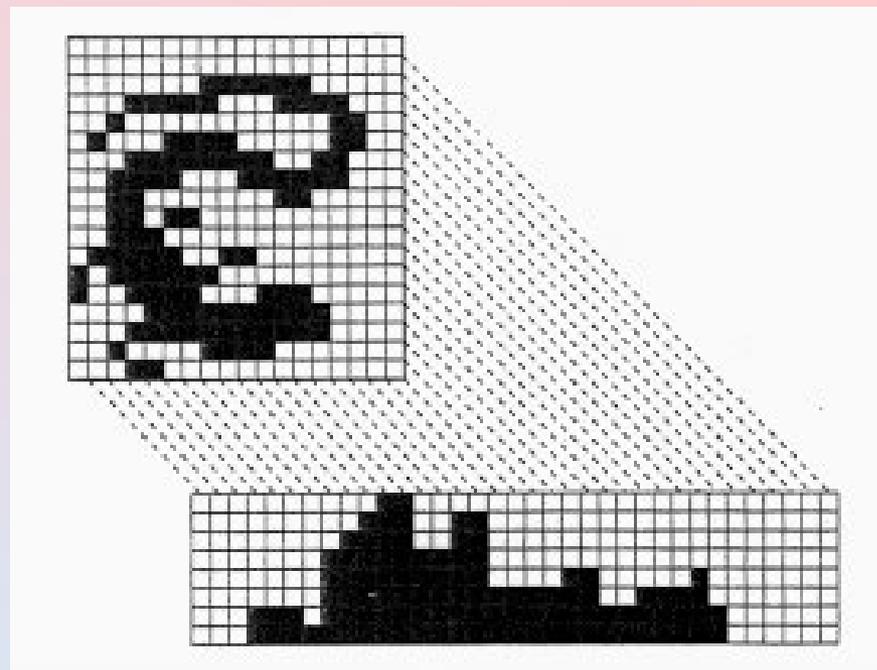
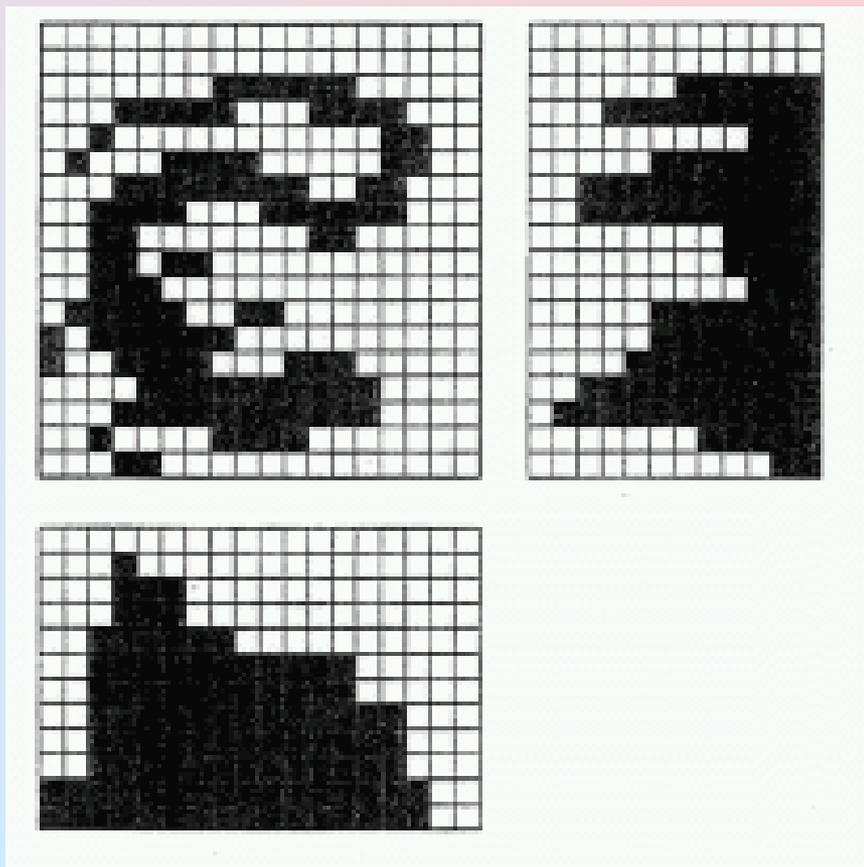
Allegro moderato.

The image displays a musical score for a String Quintet in B-flat Major, K.174, by Wolfgang Amadeus Mozart. The score is arranged in five staves: Violino I, Violino II, Viola I, Viola II, and Basso (Violoncello). The tempo is marked "Allegro moderato." To the right of the score, a vertical projection visualization is shown, labeled "projection" at the top. This visualization consists of a series of horizontal black bars of varying lengths, representing the amplitude or energy of the sound over time. The bars are aligned with the musical staves, showing the relative intensity of each instrument's contribution to the overall sound.

Examples of Projections



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Images from Machine Vision by
Jain et al.

Using Skin Color for Face Detection



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Task: Find bounding box around face in color image

Algorithm ??



Using Skin Color for Face Detection



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Find bounding box around face in color image

Algorithm: Same idea as for bat example

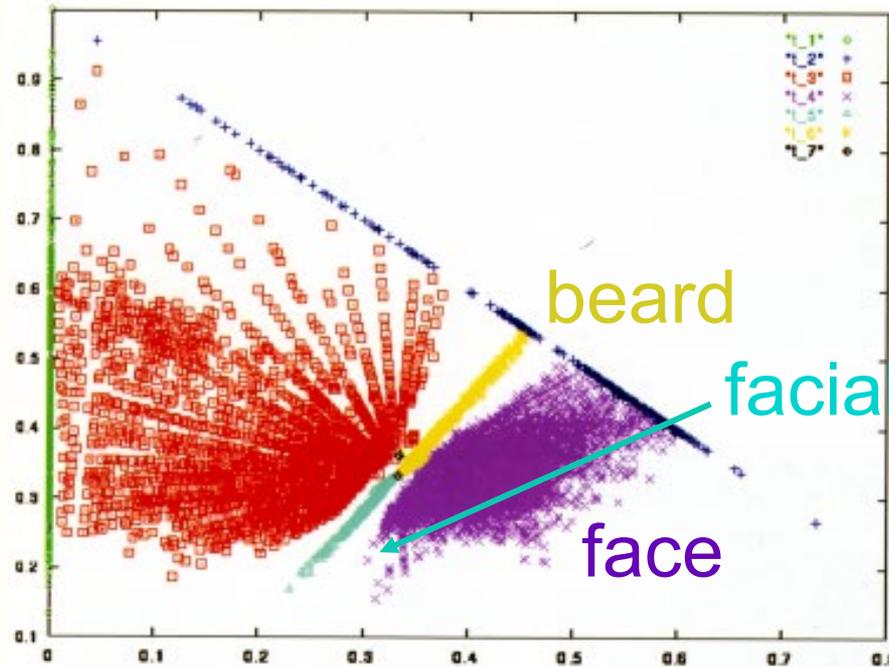
- Find all pixels with skin color
- Count number of skin color pixels in each row and column
- Analyze these histograms or projections of skin-color pixels onto x- and y-axes.



$$P1(y) = \sum_x B(x,y), \quad P2(x) = \sum_y B(x,y)$$

Normalized
Green

Using skin color for face detection



▲ Figure 6.12

Skin color clusters obtained from training: the horizontal axis is R_{norm} and the vertical axis is G_{norm} . The cluster labeled as t_4 is the primary face color, cluster t_5 and t_6 are secondary face clusters associated with shadowed or bearded areas of a face. (Figure from V. Bakic.)

▼ Figure 6.13

Face extraction examples: (left) input image; (middle) labeled image; and (right) boundaries of the extracted face region. (Images from V. Bakic.)



From Computer Vision by
Shapiro & Stockman



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Normalized
Red

Object Localization: Alternative to Projection Algorithm: “Flood Fill”



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1. Convert to binary image:



Black = “-1” pixels

White = “1” pixels

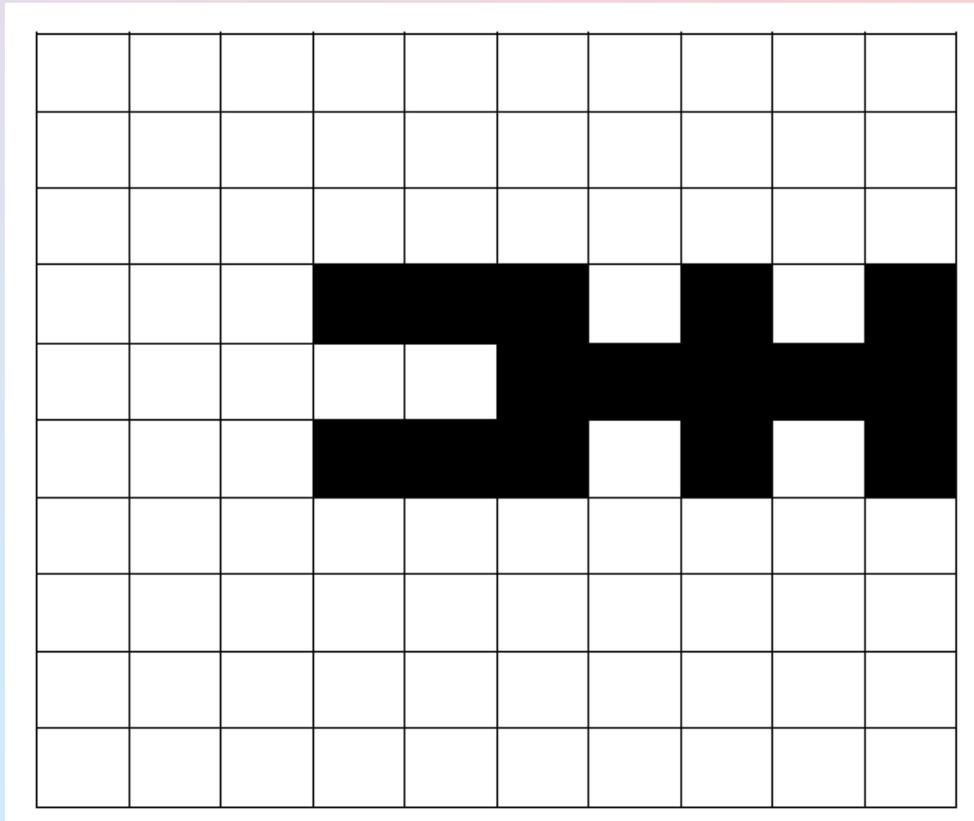
2. Scan row by row until first “-1” pixel is reached and label it “object 1.”
3. Find all neighbors of the current pixel that are “-1” and assign the object label of the current object in a recursive, depth first search manner.
4. When there are no more “-1” neighbors, continue scanning the image until the next “-1” pixel is reached and label it with the next object label and go to step 3.

Object Localization: Alternative Algorithm: “Flood Fill”



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Example



“Flood Fill” first step:



Example

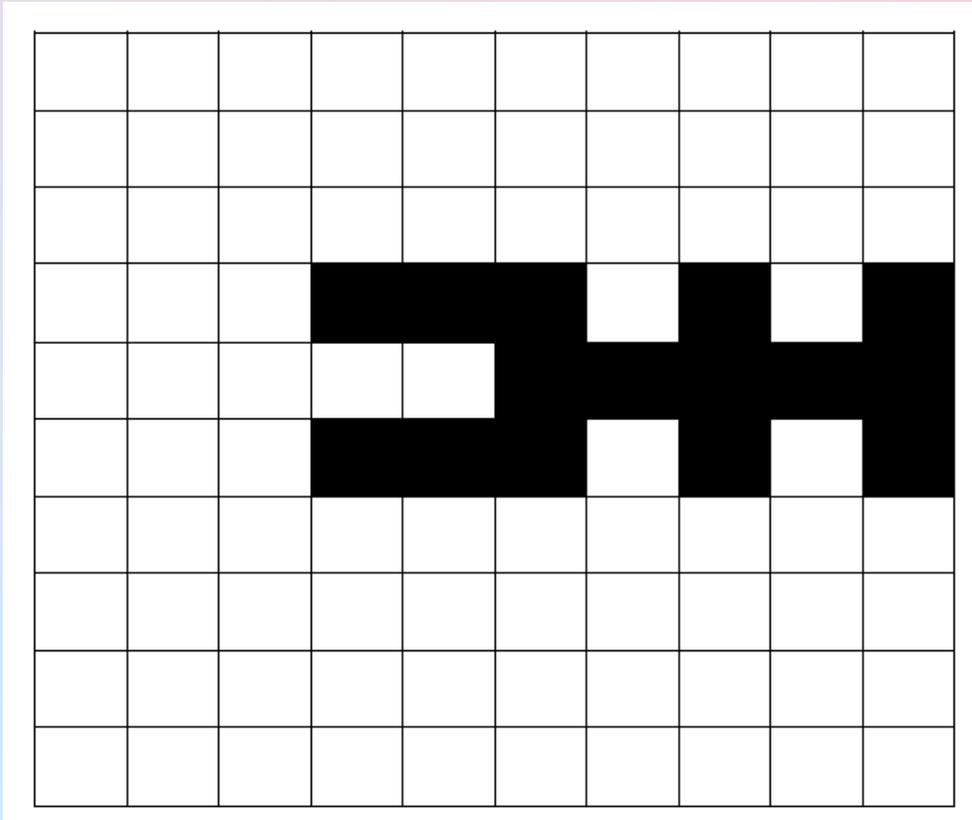
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	-1	-1	-1	1	-1	1	-1
1	1	1	1	1	-1	-1	-1	-1	-1
1	1	1	-1	-1	-1	1	-1	1	-1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1

“Flood Fill” demo



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Example



“Flood Fill” Result



Result: Red labeled pixels indicate **Object 1**

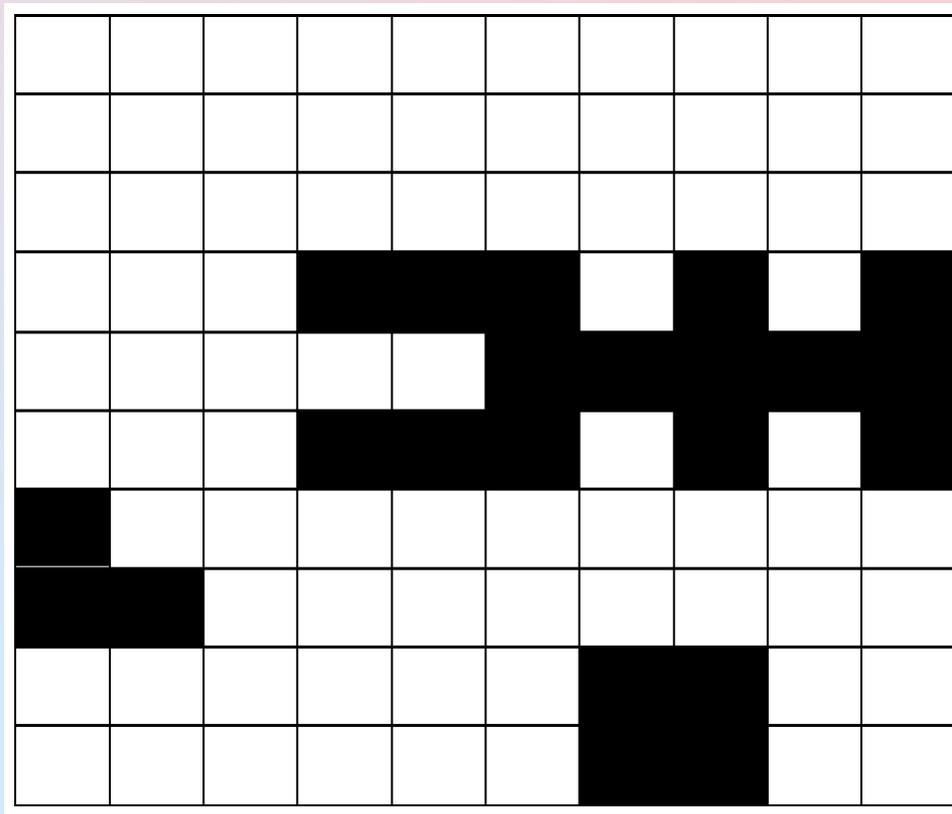
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1

“Flood Fill” as a Multiple Object Labeling Algorithm



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Example



Critique of Flood Fill Algorithm



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Critique of Flood Fill Algorithm



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- ❑ Recursive: Can lead to huge stacks



- ❑ Alternative: Sequential multi-object labeling algorithm

- 1st pass through image: Label objects based on local neighborhood
- 2nd pass solve any ambiguities

Main Ideas of Sequential Labeling Algorithm:

Scan through the image only twice.

1st scan: Determine object labels.

2nd scan: Fix cases where more than 1 label appears in an object.

During 1st scan: Find the label of pixel 'A' based on the labels of pixels 'B', 'C', and 'D':

D	C
B	A

Organize the comparison by using this 4 pixel "mask."

D	C
B	A

Sequential Labeling Algorithm

Case 1:

Neither
B, C, or D
labeled

D	C
B	A



D	C
B	ℒ

Case 2:

D labeled
B, C not

ℒ	C
B	A



ℒ	C
B	ℒ

Case 3:

Either
B or C
labeled

D	ℒ
B	A



D	ℒ
B	ℒ

D	C
ℒ	A



D	C
ℒ	ℒ

Case 4:

B, C
labeled
same different

D	ℒ
ℒ	A



D	ℒ
ℒ	ℒ

D	ℒ
ℒ	A



D	ℒ
ℒ	ℒ

Sequential Multiple Object Labeling Algorithm: 1st Phase



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1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	2	1	3
1	1	1	1	1	1	1	2'	2'	3'
1	1	1	4	4	1'	1	2'	1	3'
5	1	1	1	1	1	1	1	1	1
5	5	1	1	1	1	1	1	1	1
1	1	1	1	1	1	6	6	1	1
1	1	1	1	1	1	6	6	1	1

Label
Equivalence
Class:
1, 2, 2', 3, 3',
4, 1'

Sequential Multiple Object Labeling Algorithm: 2nd Phase



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1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
2	1	1	1	1	1	1	1	1	1
2	2	1	1	1	1	1	1	1	1
1	1	1	1	1	1	3	3	1	1
1	1	1	1	1	1	3	3	1	1

Label
Equivalence
Class:
1, 2, 2', 3, 3',
4, 1' =>
new
Label "1"

5=> 2

6=> 3

Learning Objectives



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Can explain and apply to image analysis problems:

- ❑ Circularity/elongation measure
- ❑ Projections
- ❑ Multi-object Labeling: Flood fill & sequential algorithm