

CS 512, Spring 2018, Handout 14  
Model-Checking: Temporal Logic CTL\*

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# syntax of CTL\*

Following [PMC, Sect 6.8, pp 422-427] rather than [LCS, Sect 3.5, pp 217-220]:

- **state formulas** (ranged by upper case Greek letters,  $\Phi, \Psi, \dots$ ) with  $p \in AP$ :

$$\Phi ::= \mathbf{true} \mid p \mid \neg\Phi \mid \Phi_1 \wedge \Phi_2 \mid \exists\varphi$$

- **path formulas** (ranged by lower case Greek letters,  $\varphi, \psi, \dots$ ):

$$\varphi ::= \Phi \mid \neg\varphi \mid \varphi_1 \wedge \varphi_2 \mid \bigcirc\varphi \mid \varphi_1 \uplus \varphi_2$$

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- **shorthands** (useful when using small set of primitive connectives as in [PMC])

(1) usual propositional connectives:  $\rightarrow, \vee, \leftrightarrow, \dots$ , in terms of  $\{\neg, \wedge\}$

(2)  $\diamond\varphi \triangleq \mathbf{true} \cup \varphi$

(3)  $\square\varphi \triangleq \neg\diamond\neg\varphi$

(4)  $\forall\varphi \triangleq \neg\exists\neg\varphi$

Similar shorthands as in (1), (2), and (3) hold for LTL and CTL (see [PMC, comments between Examples 6.2 and 6.3, pp 318-319]), but shorthand in (4) cannot be used in CTL (why?).

# semantics of CTL\* (syntax directed)

From [PMC, Definition 6.81, page 423] ,

the semantics of CTL\* are omitted in [LCS, Section 3.5, pages 217-221] :

- satisfaction of a **state formula** of CTL\* is defined relative to a transition system  $TS \triangleq (S, Act, \rightarrow, I, AP, L)$  and a state  $s \in S$

1.  $TS, s \models \mathbf{true}$

2.  $TS, s \models p$       iff       $p \in L(s)$

3.  $TS, s \models \neg\Phi$       iff       $TS, s \not\models \Phi$

4.  $TS, s \models \Phi \wedge \Psi$       iff       $TS, s \models \Phi$  and  $TS, s \models \Psi$

5.  $TS, s \models \exists\varphi$       iff       $TS, \pi \models \varphi$  for some path  $\pi$  starting at  $s$

## semantics of CTL\* (syntax directed)

- satisfaction of a **path formula** of CTL\* is defined relative to a transition system  $TS \triangleq (S, Act, \rightarrow, I, AP, L)$  and a path  $\pi \triangleq s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$

1.  $TS, \pi \models \Phi$  iff  $TS, s_0 \models \Phi$
2.  $TS, \pi \models \neg\varphi$  iff  $TS, \pi \not\models \varphi$
3.  $TS, \pi \models \varphi_1 \wedge \varphi_2$  iff  $TS, \pi \models \varphi_1$  and  $TS, \pi \models \varphi_2$
4.  $TS, \pi \models \bigcirc \varphi$  iff  $TS, \pi[1..] \models \varphi$
5.  $TS, \pi \models \varphi_1 \uplus \varphi_2$  iff there is  $n \geq 0$  such that  
 $TS, \pi[n..] \models \varphi_2$   
and for every  $0 \leq k < n$  it holds that  
 $TS, \pi[k..] \models \varphi_1$

# semantics of CTL\*

- CTL\* semantics for transition systems  $TS \triangleq (S, Act, \rightarrow, I, AP, L)$  from [PMC, Definition 6.82, page 423]:
  - ▶ given a **state formula**  $\Phi$  of CTL\*:

$$TS \models \Phi \quad \text{iff} \quad TS, s \models \Phi \quad \text{for every } s \in I$$

- ▶ given a **path formula**  $\varphi$  of CTL\*:

$$TS \models \varphi \quad \text{iff} \quad TS, \pi \models \varphi \quad \text{for every path } \pi \text{ starting at some } s \in I$$

# LTL and CTL are sublogics of CTL\*

- ▶ LTL is a “subset” of CTL\*

because a LTL formula  $\varphi$  is equivalent to the CTL\* formula  $\forall\varphi$

(this requires a rigorous proof, [PMC, Theorem 6.83, page 424],  
based on the formal semantics of CTL\*)

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- ▶ CTL is a subset of CTL\*

because we can restrict paths formulas to be of the form

$$\varphi ::= \bigcirc \Phi \mid \Phi \mid \Phi \cup \Phi$$

(check that this restriction on  $\varphi$  corresponds to enforcing the requirement that every **temporal connective** must be coupled with a **quantifier**)



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