Guarded Recursive Datatype Constructors

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ABSTRACT

We introduce a notion of guarded recursive (g.r.) datatype constructors, generalizing the notion of recursive datatypes in functional programming languages such as ML and Haskell. We address both theoretical and practical issues resulted from this generalization. On one hand, we design a type system to formalize the notion of g.r. datatype constructors and then prove the soundness of the type system. On the other hand, we present some significant applications (e.g., implementing objects, implementing staged computation, etc.) of g.r. datatype constructors, arguing that g.r. datatype constructors can have far-reaching consequences in programming. The main contribution of the paper lies in the recognition and then the formalization of a programming notion that is of both theoretical interest and practical use.

Categories and Subject Descriptors

D.3.2 [**Programming Languages**]: Language Classifications—*Applicative Languages*; D.3.3 [**Programming Languages**]: Language Constructs and Features—*Datatypes and Structures*

General Terms

Languages, Theory

Keywords

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1. INTRODUCTION

Although we have since found a variety of applications of guarded recursive (g.r.) datatype constructors, we initially encountered this notion in a study on run-time typepassing. In parametric polymorphism, there is no facility

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for a polymorphic function to inspect its type arguments and such a function behaves uniformly on all possible type arguments. As a consequence, there is no need for passing types at run-time. However, there are numerous occasions in practice where we would want polymorphic functions to behave differently on different type arguments. This is often called ad-hoc polymorphism. For instance, we may want to implement a function *val2string* for converting run-time values into string representations. In order to construct such a function, we need to analyze the types of values at run-time. With run-time type analysis, we can also support various advanced implementation techniques such as flattened data representation [10], polymorphic marshaling [16], unboxed function arguments [12], tag-free garbage collection [20], etc.

A (conceptually) simple and direct approach to run-time type analysis is to pass types or, more precisely, terms representing types at run-time and then inspect the structure of such terms. In order to capture the relation between a type and its term representation, we can declare a g.r. datatype constructor TY as follows.

```
typecon (type) TY =
  (int) TYint
| {'a,'b}.('a * 'b) TYtup of 'a TY * 'b TY
| {'a,'b}.('a -> 'b) TYfun of 'a TY * 'b TY
| {'a}.('a TY) TYtyp of 'a TY
```

The syntax typecon (type) TY means that TY is a type constructor of the kind $* \rightarrow *$, that is, TY takes one type to form another type. There are four value constructors TYint, TYtup, TYfun and TYtyp associated with TY, which are assigned the following types.

```
\begin{array}{rcl} TYint & : & (int) TY \\ TYtup & : & \forall \alpha \forall \beta.(\alpha) TY * (\beta) TY \rightarrow (\alpha * \beta) TY \\ TYfun & : & \forall \alpha \forall \beta.(\alpha) TY * (\beta) TY \rightarrow (\alpha \rightarrow \beta) TY \\ TYtyp & : & \forall \alpha \forall \beta.(\alpha) TY \rightarrow ((\alpha) TY) TY \end{array}
```

For instance, the following value,

```
TYfun(\langle TYtup(\langle TYint, TYint \rangle), TYint \rangle)
```

which has the type (int * int \rightarrow int)TY, represents the type int * int \rightarrow int. In general, a value of the type (τ) TY represents the type τ . Now we can implement the *val2string* function as follows.

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The withtype clause in the definition is a type annotation, which assigns the type $\forall \alpha.(\alpha) TY \rightarrow \alpha \rightarrow \text{string}$ to the defined function *val2string*.

The above idea of using terms to represent types can already be found in [6, 22], where a typed calculus λ_R is introduced to facilitate type-passing. The type constructor R in λ_R corresponds to TY, and its associated value constructors $R_{int}, R_{\times}, R_{\rightarrow}$ and R_R correspond to TYint, TYtup, TYfunand TYtyp, respectively. However, with g.r. datatype constructors, we can also form interesting and useful types that cannot be handled in λ_R . For instance, we can declare a g.r. datatype constructors HOAS as follows.

```
typecon (type) HOAS =
  {'a}. ('a)HOASlift of 'a
  {'a,'b}. ('a * 'b)HOAStup of 'a HOAS * 'b HOAS
  {'a.'b}. ('a -> 'b)HOAStup of 'a HOAS -> 'b HOAS
  {'a,'b}. ('b)HOASapp of ('a -> 'b) HOAS * 'a HOAS
  {'a,'b}. ('a)HOASfix of 'a HOAS -> 'a HOAS
```

This declaration indicates that HOAS is a unary type constructor, and the value constructors associated with HOASare assigned the types in Figure 1. The type constructor HOAS, which is intended to construct types for a form of higher-order abstract syntax trees [4, 18], *cannot* be inductively defined because of the type of the value constructor HOAS is the type for higherorder abstract syntax trees representing monomorphically typed expressions of the type τ . For instance, the following expression in ML, which has the type $(int \rightarrow int) \rightarrow int \rightarrow$ int,

fn (x:int \rightarrow int) \Rightarrow fn (y:int) \Rightarrow x(y)

can be represented as follows:

```
HOASlam(fn (x:(int -> int) HOAS) =>
HOASlam (fn (y:int HOAS) => HOASapp (x, y)))
```

Note that the type of the above expression is $((\texttt{int} \rightarrow \texttt{int}) \rightarrow \texttt{int} \rightarrow \texttt{int})HOAS$. Furthermore, we can implement the following function *eval* for evaluating higher-order abstract syntax trees.

```
fun eval (HOASlift v) = v
  | eval (HOAStup (e1, e2)) = (eval e1, eval e2)
  | eval (HOASlam f) = fn x => eval (f (HOASlift x))
  | eval (HOASapp (e1, e2)) = (eval e1) (eval e2)
  | eval (e as HOASfix f) = eval (f e)
withtype {'a}. 'a HOAS -> 'a
```

Note *eval* is assigned the type $\forall \alpha.(\alpha) HOAS \rightarrow \alpha$, indicating that the evaluation of higher-order abstract syntax trees is type-preserving. Later, we will show that the type constructor HOAS can play a key rôle in implementing staged computation [7, 19].

The introduction of g.r. datatype constructors raises a number of theoretical and practical issues. We briefly outline our results and design decisions.

The first and foremost issue that arises is the formalization of g.r. datatype constructors in type theory. We show how fixed-point operators over type constructors of higher kinds can be used to formally define g.r. datatype constructors. In particular, we show how the standard fold/unfold operations (for recursive types) and injection operations (for sum types) can be used to define the value constructors associated with a declared g.r. datatype constructor.

The second issue is the decidability and practicality of type-checking in the presence of g.r. datatype constructors. We address this question in two steps. We first present an explicitly typed (and overly verbose) internal language $\lambda_{2,G\mu}$ in which type-checking can be handled straightforwardly. We next present an external language $ML_{2,G\mu}$, a slightly extended fragment of ML, and then mention an elaboration process from $ML_{2,G\mu}$ to $\lambda_{2,G\mu}$ that preserves the standard operational semantics. When programming in $ML_{2,G\mu}$, the programmer may omit writing types at various occasions (determined by the elaboration process).

The third issue is the usefulness of g.r. datatype constructors in practice. We present various examples to illustrate some interesting applications of g.r. datatype constructors in capturing program invariants. In particular, we show that g.r. datatype constructors can be combined with a restricted form of dependent types [25, 23] to type programming objects, overcoming some significant deficiencies in many existing type systems for object-oriented programming [2].

In summary, we present a generalization of the notion of recursive datatypes, allowing the programmer to form g.r. datatype constructors. The most significant contribution of the paper lies in the recognition of such a simple and natural generalization that can have far-reaching consequences in programming. We formalize the notion of g.r. datatype constructors in a type system and then establish the type soundness of the type system, which constitutes the main technical contribution of the paper. We also present various realistic and interesting examples in support of the introduction of g.r. datatype constructors into a programming language.

We organize the rest of the paper as follows. In Section 2, we introduce an internal language $\lambda_{2,G\mu}$ to formalize the notion of g.r. datatype constructors, presenting both static and dynamic semantics for $\lambda_{2,G\mu}$ and proving its type soundness. We next form an external language $ML_{2,G\mu}$ in Section 3 and then mention an elaboration process from $ML_{2,G\mu}$ to $\lambda_{2,G\mu}$ to support unobtrusive programming. We use some interesting examples in Section 4 to illustrate various applications of g.r. datatype constructors. Lastly, we mention some future research directions and related works.

There is a full version of the paper on-line [24], where various omitted details can be found.

2. THE LANGUAGE $\lambda_{2,G\mu}$

We present a language $\lambda_{2,G\mu}$ based on the explicitly typed second-order polymorphic λ -calculus. We present both static and dynamic semantics for $\lambda_{2,G\mu}$ and then show that the type system of $\lambda_{2,G\mu}$, which supports g.r. datatype constructors, is sound.

The language $\lambda_{2,G\mu}$ is designed to be an internal language. Later, we will also present an external language $ML_{2,G\mu}$ and mention an elaboration process from $ML_{2,G\mu}$ to $\lambda_{2,G\mu}$. When programming in $ML_{2,G\mu}$, the programmer may omit writing certain types, which can be reconstructed through the elaboration process.

2.1 Syntax

We present the syntax for $\lambda_{2,G\mu}$ in Figure 2, which is mostly standard. We use α for type variables, **1** for the unit type and $\vec{\tau}$ for a (possibly empty) sequence of types τ_1, \ldots, τ_n . We have two kinds of expression variables: x for lam-variables and f for fix-variables. We use xf for either a lam-variable or a fix-variable. We can only form a λ abstraction over a lam-variable and a fixed-point expression over a fix-variable. Note that a lam-variable is a value but a fix-variable is not. We use c for constructors and assume that every constructor is unary.¹ Also, we require that the

¹For a constructor taking no argument, we can treat it as a

 $\begin{array}{lll} HOASlift & : & \forall \alpha. \alpha \rightarrow (\alpha) HOAS \\ HOAStup & : & \forall \alpha \forall \beta. (\alpha) HOAS \ast (\beta) HOAS \rightarrow (\alpha \ast \beta) HOAS \\ HOASlam & : & \forall \alpha \forall \beta. ((\alpha) HOAS \rightarrow (\beta) HOAS) \rightarrow (\alpha \rightarrow \beta) HOAS \\ HOASapp & : & \forall \alpha \forall \beta. (\alpha \rightarrow \beta) HOAS \ast (\alpha) HOAS \rightarrow (\beta) HOAS \\ HOASfix & : & \forall \alpha. ((\alpha) HOAS \rightarrow (\alpha) HOAS) \rightarrow (\alpha) HOAS \end{array}$

Figure 1: The value constructors associated with HOAS and their types

types	au	::=	$\alpha \mid 1 \mid \tau_1 * \tau_2 \mid \tau_1 \to \tau_2 \mid$
			$(\vec{\tau})T \mid \forall \alpha. \tau$
patterns	p	::=	$x \mid \langle \rangle \mid \langle p_1, p_2 \rangle \mid c[\vec{\alpha}](p)$
clauses	ms	::=	$(p_1 \Rightarrow e_1 \mid \dots \mid p_n \Rightarrow e_n)$
expressions	e	::=	$x \mid f \mid c[\vec{\tau}](e)$
			$\langle \rangle \mid \langle e_1, e_2 \rangle \mid \mathbf{fst}(e) \mid \mathbf{snd}(e) \mid$
			$\lambda x : \tau . e \mid e_1(e_2) \mid \Lambda \alpha . v \mid e[\tau] \mid$
			fix $f : \tau . v \mid \mathbf{case} \ e \ \mathbf{of} \ ms \mid$
			let $x = e_1$ in e_2 end
values	v	::=	$x \mid c[\vec{\tau}](v) \mid \langle \rangle \mid \langle v_1, v_2 \rangle \mid$
			$\lambda x : \tau.e \mid \Lambda \alpha.v$
exp. var. ctx.	Γ	::=	$\cdot \mid \Gamma, x: au$
typ. var. ctx.	Δ	::=	$\cdot \mid \Delta, \alpha \mid \Delta, \tau_1 \equiv \tau_2$

Figure 2: Syntax for the internal language $\lambda_{2,G\mu}$

body of either Λ or fix be a value. The syntax for patterns is to be explained in Section 2.3.

We use Θ for substitutions mapping type variables to types and $\mathbf{dom}(\Theta)$ for the domain of Θ . Note that $\Theta[\alpha \mapsto \tau]$, where we assume $\alpha \notin \mathbf{dom}(\Theta)$, extends Θ with a mapping from α to τ . Similar notations are also used for substitutions θ mapping variables xf to expressions. We write $\bullet[\Theta]$ ($\bullet[\theta]$) for the result of applying Θ (θ) to \bullet , where \bullet can be a type, an expression, a type variable context, an expression variable context, etc.

We use Δ for type variable contexts in $\lambda_{2,G\mu}$. As usual, we can declare a type variable α in a type variable context Δ . We use $\Delta \vdash \tau$: * to mean that τ is a well-formed type in which every type variable is declared in Δ . All type formation rules are standard and thus omitted. We can also declare a type equality $\tau_1 \equiv \tau_2$ in Δ . Intuitively, when deciding type equality under Δ , we assume that the types τ_1 and τ_2 are equal if $\tau_1 \equiv \tau_2$ is declared in Δ .

Given two types τ_1 and τ_2 , we write $\tau_1 = \tau_2$ to mean that τ_1 is α -equivalent to τ_2 . The following rules are for deriving judgments of the form $\vdash \Theta : \Delta$, which roughly means that Θ matches Δ .

$$\frac{1}{\vdash []:\cdot} \quad \frac{\vdash \Theta : \Delta \quad \vdash \tau : *}{\vdash \Theta[\alpha \mapsto \tau] : \Delta, \alpha} \quad \frac{\vdash \Theta : \Delta \quad \tau_1[\Theta] = \tau_2[\Theta]}{\vdash \Theta : \Delta, \tau_1 \equiv \tau_2}$$

We use $\Delta \models \tau_1 \equiv \tau_2$ for a type constraint; this constraint is satisfied if we have $\vdash \tau_1[\Theta] \equiv \tau_2[\Theta]$ for every Θ such that $\vdash \Theta : \Delta$ is derivable. As can be expected, we have the following proposition.

Proposition 2.1.

- If $\Delta \vdash \tau : *$ is derivable, then $\Delta \models \tau \equiv \tau$ holds.
- If $\Delta \models \tau_1 \equiv \tau_2$ holds, then $\Delta \models \tau_2 \equiv \tau_1$ also holds.
- If $\Delta \models \tau_1 \equiv \tau_2$ and $\Delta \models \tau_2 \equiv \tau_3$ hold, then $\Delta \models \tau_1 \equiv \tau_3$ also holds.

constructor taking the unit $\langle \rangle$ as its argument.

Pattern typing rules $\Delta_0 \vdash p \downarrow \tau \Rightarrow (\Delta; \Gamma)$ $\frac{\Delta_0 \vdash \tau : *}{\Delta_0 \vdash x \downarrow \tau \Rightarrow \cdot; x : \tau} \text{ (pat-var)}$ $\frac{\Delta_0 \vdash p_1 \downarrow \tau_1 \Rightarrow \Delta_1; \Gamma_1 \quad \Delta_0 \vdash p_2 \downarrow \tau_2 \Rightarrow \Delta_2; \Gamma_2}{\Delta_0 \vdash \langle p_1, p_2 \rangle \downarrow \tau_1 * \tau_2 \Rightarrow \Delta_1, \Delta_2; \Gamma_1, \Gamma_2} \text{ (pat-tup)}$ $\frac{\Sigma(c) = \forall \vec{\alpha}. \tau \rightarrow (\vec{\tau}_1)T}{\Delta_0, \vec{\alpha}. \vec{\tau}_1 \equiv \vec{\tau}_2 \vdash p \downarrow \tau \Rightarrow \Delta; \Gamma} \text{ (pat-cons)}$ Clause typing rule $\Delta; \Gamma \vdash p \Rightarrow e : \tau_1 \Rightarrow \tau_2$ $\frac{\Delta \vdash p \downarrow \tau_1 \Rightarrow (\Delta'; \Gamma') \quad \Delta, \Delta'; \Gamma, \Gamma' \vdash e : \tau_2}{\Delta; \Gamma \vdash p \Rightarrow e : \tau_1 \Rightarrow \tau_2}$ Clauses typing rule $\Delta; \Gamma \vdash ms : \tau_1 \Rightarrow \tau_2$ $\frac{\Delta; \Gamma \vdash p_i \Rightarrow e_i : \tau_1 \Rightarrow \tau_2 \text{ for } i = 1, \dots, n}{\Delta; \Gamma \vdash (p_1 \Rightarrow e_1 \mid \cdots \mid p_n \Rightarrow e_n) : \tau_1 \Rightarrow \tau_2}$

Figure 3: Pattern typing rules

Expression typing rules
$$\Delta; \Gamma \vdash e: c$$

$$\begin{split} \frac{\Delta \models \tau_1 \equiv \tau_2 \quad \Delta; \Gamma \vdash e: \tau_1}{\Delta; \Gamma \vdash e: \tau_2} \quad (\text{ty-eq}) \\ \frac{\Gamma(xf) = \tau}{\Delta; \Gamma \vdash xf: \tau} \quad (\text{ty-var}) \\ \frac{\Sigma(c) = \forall \vec{\alpha}. \tau_1 \rightarrow \tau_2 \quad \Delta \vdash \vec{\tau}: \vec{*}}{\Delta; \Gamma \vdash c: \tau_1[\vec{\alpha} \mapsto \vec{\tau}]} \quad (\text{ty-cons}) \\ \frac{\Sigma(c) = \forall \vec{\alpha}. \tau_1 \rightarrow \tau_2 \quad \Delta \vdash \vec{\tau}: \vec{*}}{\Delta; \Gamma \vdash c: \tau_1[\vec{\alpha} \mapsto \vec{\tau}]} \quad (\text{ty-cons}) \\ \frac{\Delta; \Gamma \vdash c: \tau_1[\vec{\alpha} \mapsto \vec{\tau}]}{\Delta; \Gamma \vdash c_1: \tau_1 \quad \Delta; \Gamma \vdash e_2: \tau_2} \quad (\text{ty-tup}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \times \tau_2}{\Delta; \Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2} \quad (\text{ty-tup}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 * \tau_2}{\Delta; \Gamma \vdash \text{snd}(e) : \tau_1} \quad (\text{ty-shd}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \times \tau_2}{\Delta; \Gamma \vdash \text{snd}(e) : \tau_2} \quad (\text{ty-shd}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \rightarrow \tau_2 \quad \Delta; \Gamma \vdash e: \tau_2}{\Delta; \Gamma \vdash e_1(e_2) : \tau_2} \quad (\text{ty-app}) \\ \frac{\Delta; \Gamma \vdash e: \forall \alpha. \tau \quad \Delta \vdash \tau_1: *}{\Delta; \Gamma \vdash \alpha. e: \forall \alpha. \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \forall \alpha. \tau \quad \Delta \vdash \tau_1: *}{\Delta; \Gamma \vdash e: \tau_1} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-tapp}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{fx} f: \tau. e: \tau} \quad (\text{ty-case}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{case} e \text{ of } ms: \tau_2} \quad (\text{ty-case}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{case} e \text{ of } ms: \tau_2} \quad (\text{ty-case}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{case} e \text{ of } ms: \tau_2} \quad (\text{ty-case}) \\ \frac{\Delta; \Gamma \vdash e: \tau_1 \quad \Delta; \Gamma \vdash ms: \tau_1 \Rightarrow \tau_2}{\Delta; \Gamma \vdash \text{case} } \quad (\text{ty-case}) \\ \frac$$

	Figure 4:	Typing	rules f	for	expressions
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At this moment, there is no need to be concerned with how type constraints can be solved; we may simply assume the existence of an oracle for doing this. In Section 3, we will present a complete procedure for solving type constraints.

2.2 G.R. Datatype Constructors

We use * as the kind for types and $(*, \ldots, *) \to *$ as the kind for type constructors of arity n, where n the number of the occurrences of * in $(*, \ldots, *)$. We use T for a recursive type constructor of arity n and associate with T a list of (value) constructors c_1, \ldots, c_k ; for each $1 \leq i \leq k$, the type of c_i is of the form $\forall \vec{\alpha}_i.\tau_i \to (\vec{\tau}_i)T$, where $\vec{\tau}_i$ is for a sequence of types $\tau_1^i, \ldots, \tau_{n_i}^i$, and $\forall \vec{\alpha}_i$ stands for a (possibly empty) sequence of quantifiers $\forall \alpha_1^i \ldots \forall \alpha_{m_i}^i$ (assuming $\vec{\alpha}_i = \alpha_1^i, \ldots, \alpha_{m_i}^i$). In our concrete syntax, T can be declared as follows.

$$typecon (type, ..., type) T = \{\vec{\alpha}_1\}.(\vec{\tau}_1) c_1 \text{ of } \tau_1 \\ | \{\vec{\alpha}_2\}.(\vec{\tau}_2) c_2 \text{ of } \tau_2 \\ | ... \\ | \{\vec{\alpha}_k\}.(\vec{\tau}_n) c_k \text{ of } \tau_k \}$$

We write $\exists \Delta . \tau$ for a guarded type, where Δ is a type variable context that may contain some type equalities. We use the name guard for such a type equality. For instance, $\exists \Delta_1 . \tau$ is a guarded type, where $\Delta_1 = (\alpha_1, \alpha_2, \alpha_1 * \alpha_2 \equiv \texttt{int} * \texttt{bool})$ and $\tau = \alpha_1 * \alpha_1$; this type is equivalent to int * int sincewe must map α_1 to int in order to satisfy the type equality $\alpha_1 * \alpha_2 \equiv \texttt{int} * \texttt{bool}$. The type $\exists \Delta_2 . \tau$ is also a guarded type, where $\Delta_2 = (\alpha_1, \alpha_2, \alpha_1 * \alpha_2 \equiv \texttt{int})$; this type is equivalent to the type void, i.e., the type int which there is no element, since the type equality $\alpha_1 * \alpha_2 \equiv \texttt{int}$ cannot be satisfied. For $\Delta = (\alpha_1, \alpha_2, \alpha_1 * \alpha_2 \equiv \alpha)$, we observe that the type constructor $\lambda \alpha \exists \Delta . \tau$ has the following interesting feature: when applied to a type τ_0 , the type constructor forms a type that is equivalent to $\tau_1 * \tau_1$ if τ_0 is of the form $\tau_1 * \tau_2$, or void otherwise.

We show that the type constructor T can be formally defined as $\mu t.\sigma$, where σ is the following sum of guarded types. Therefore, we call T a guarded recursive datatype constructor.

$$\mu t.\lambda \vec{\alpha}.(\exists \{\vec{\alpha}_1, \vec{\tau}_1 \equiv \vec{\alpha}\}.\tau_1 + \ldots + \exists \{\vec{\alpha}_k, \vec{\tau}_k \equiv \vec{\alpha}\}.\tau_k)$$

Note that for i = 1, ..., k, $\vec{\alpha} = \alpha_1, ..., \alpha_n$ and $\vec{\alpha}_i$ are assumed to share no common type variables, and the *T*'s in $\vec{\tau}_i$ and τ_i have been replaced with *t*'s.

Given a type variable context Δ , we define $|\Delta|$ as follows.

$$|\cdot| = \cdot |\Delta, \alpha| = |\Delta|, \alpha |\Delta, \tau_1 \equiv \tau_2| = |\Delta|$$

For a type substitution Θ and a sequence of type variables $\vec{\alpha} = \alpha_1, \ldots, \alpha_n$, we write $\Theta(\vec{\alpha})$ for $\Theta(\alpha_1), \ldots, \Theta(\alpha_n)$. The introduction and elimination rules for guarded types can be formed as follows.

$$\frac{\Delta_1; \Gamma \vdash e: \tau[\Theta] \quad \Delta_1 \vdash \Theta: \Delta_2}{\Delta_1; \Gamma \vdash \langle \Theta(|\Delta_2|) \mid e \rangle: \exists \Delta_2. \tau} \quad (\exists\text{-intro})$$

$$\frac{\Delta_1; \Gamma \vdash e_1: \exists \Delta_2. \tau_1 \quad \Delta_1, \Delta_2; \Gamma, x: \tau_1 \vdash e_2: \tau_2}{\Delta_1; \Gamma \vdash \text{ open } e_1 \text{ as } \langle |\Delta_2| \mid x \rangle \text{ in } e_2: \tau_2} \quad (\exists\text{-elim})$$

Note that a judgment of the form $\Delta_1 \vdash \Theta : \Delta$ means that $\mathbf{dom}(\Theta) = \mathbf{dom}(\Delta_2)$ and $\Delta_1 \models \tau_1[\Theta] \equiv \tau_2[\Theta]$ for each type equality $\tau_1 \equiv \tau_2$ in Δ_2 . In the elimination rule, we require that τ_2 contain no type variable in $\mathbf{dom}(\Delta_2)$.

Given types τ^1, \ldots, τ^k and $1 \le i \le k$, we use $inj_i^{\tau^1 + \ldots + \tau^k}$ for the *i*th injection that injects values of the type τ^i into values of the type $\tau^1 + \ldots + \tau^k$. In addition, we use $unfold((\vec{\tau})T)$ for the expansion of $(\vec{\tau})T$ to $\sigma[t \mapsto T][\vec{\alpha} \mapsto \vec{\tau}]$, where $\vec{\tau}$ is a

$$\frac{\vec{\alpha}_{i}; x:\tau_{i} \vdash x:\tau_{i} \quad \vec{\alpha}_{i} \vdash [\vec{\beta}_{i} \mapsto \vec{\alpha}_{i}]:\vec{\beta}_{i}, \vec{\tau}_{i}[\vec{\alpha}_{i} \mapsto \vec{\beta}_{i}] \equiv \vec{\tau}_{i}}{\vec{\alpha}_{i}; x:\tau_{i} \vdash \langle \vec{\alpha}_{i} \mid x \rangle: \exists \{\vec{\beta}_{i}, \vec{\tau}_{i}[\vec{\alpha}_{i} \mapsto \vec{\beta}_{i}] \equiv \vec{\tau}_{i}\}, \tau_{i}[\vec{\alpha}_{i} \mapsto \vec{\beta}_{i}]} (\exists \text{-intro}) \\
\frac{\vec{\alpha}_{i}; x:\tau_{i} \vdash inj_{i}^{unfold((\vec{\tau}_{i})T)}(\langle \vec{\alpha}_{i} \mid x \rangle): unfold((\vec{\tau}_{i})T)}{\vec{\alpha}_{i}; x:\tau_{i} \vdash inj_{i}^{unfold((\vec{\tau}_{i})T)}(\langle \vec{\alpha}_{i} \mid x \rangle): (\vec{\tau}_{i})T} (\mathsf{fold}) \\
\frac{\vec{\alpha}_{i}; x:\tau_{i} \vdash inj_{i}^{unfold((\vec{\tau}_{i})T)}(\langle \vec{\alpha}_{i} \mid x \rangle): (\vec{\tau}_{i})T}{\vec{\alpha}_{i}; \mapsto \lambda x: \tau_{i}.inj_{i}^{unfold((\vec{\tau}_{i})T)}(\langle \vec{\alpha}_{i} \mid x \rangle): \tau_{i} \to (\vec{\tau}_{i})T} (\forall \text{-intro}) \\
\vdots \vdash \Lambda \vec{\alpha}_{i}.\lambda x:\tau_{i}.inj_{i}^{unfold((\vec{\tau}_{i})T)}(\langle \vec{\alpha}_{i} \mid x \rangle): \forall \vec{\alpha}_{i}.\tau_{i} \to (\vec{\tau}_{i})T \end{cases} (\forall \text{-intro})$$

Figure 5: Defining value constructors associated with T

sequence of *n* types. Then we can construct a typing derivation in Figure 5, where all the applied rules are standard. By the derivation, we can define c_i as follows for i = 1, ..., k:

$$\Lambda \vec{\alpha}_i . \lambda x : \tau_i . inj_i^{unfold((\vec{\tau}_i)T)} \langle \vec{\alpha}_i \mid x \rangle$$

Therefore, we have justified the notion of g.r. datatype constructors in terms of standard type-theoretical concepts.

We now present some simple examples of g.r. datatype constructors so as to facilitate the understanding of this concept.

Example 1 The following syntax

typecon TOP = Top of 'a

declares a value constructor *Top* of the type $\forall \alpha.\alpha \to TOP$; *TOP* is defined as $\mu t.\exists \{\alpha\}.\alpha$, which is equivalent to $\exists \alpha.\alpha$.

The type TOP is called an abstract datatype in [11]. In general, the the notion of abstract datatypes is subsumed by the notion of g.r. datatype constructors.

Example 2 The following syntax

```
typecon (type) list =
  ('a) nil | ('a) cons of 'a * 'a list
```

declares two constructors *nil* and *cons* of the types $\forall \alpha. \mathbf{1} \rightarrow (\alpha) list$ and $\forall \alpha. \alpha * (\alpha) list \rightarrow (\alpha) list$, respectively; the type constructor *list* is define as follows, which is essentially equivalent to the type constructor $\mu t.\lambda \alpha. \mathbf{1} + \alpha * (\alpha) t$.

$$\mu t.\lambda \alpha. \exists \{\alpha_1, \alpha_1 \equiv \alpha\}. \mathbf{1} + \exists \{\alpha_2, \alpha_2 \equiv \alpha\}. \alpha_2 * (\alpha_2) t$$

Note that the usual list type constructor in ML is defined as $\lambda \alpha.\mu t.\mathbf{1} + \alpha * t.$

In the rest of the paper, we are no longer in need of guarded types of the form $\exists \Delta . \tau$ directly. The typing rules (\exists -intro) and (\exists -elim) are to be absorbed into the typing rules (ty-cons) and (ty-case), respectively. Similarly, we we will make no use of expressions of the form $\langle \vec{\tau} | e \rangle$ or the form open e_1 as $\langle \vec{\alpha} | x \rangle$ in e_2 directly.

2.3 Pattern Matching

We use p for patterns. As usual, a type (value) variable may occur at most once in each pattern. We use a judgment of the form $v \downarrow p \vdash (\Theta; \theta)$ to mean that matching a value v against a pattern p yields substitutions Θ and θ for the type and value variables in p. The rules for deriving such judgments are listed as follows.

Given a type variable context Δ_0 , a pattern p and a type τ , we can use the rules in Figure 3 to derive a judgment of the form $\Delta_0 \vdash p \downarrow \tau \Rightarrow (\Delta; \Gamma)$, whose meaning is formally captured by Lemma 2.3.

2.4 Static and Dynamic Semantics

We present the typing rules for $\lambda_{2,G\mu}$ in Figure 4. We assume the existence of a signature Σ in which the types of constructors are declared.

Most of the typing rules are standard. The rule (ty-eq) indicates that the type equality in $\lambda_{2,G\mu}$ is modulo type constraint solving. Please notice the great difference between the rules presented in Figure 3 for typing clauses and the "standard" ones in [14].

We form the dynamic semantics of $\lambda_{2,G\mu}$ through the use of evaluation contexts, which are defined below.

Evaluation context E ::= $[] | \mathbf{fst}(E) | \mathbf{snd}(E) | \langle E, e \rangle | \langle v, E \rangle | E(e) | v(E) |$ $E[\tau] | \mathbf{let} \ x = E \ \mathbf{in} \ e \ \mathbf{end} | \mathbf{case} \ E \ \mathbf{of} \ ms$

DEFINITION 2.2. A redex is defined as follows.

- $\mathbf{fst}(\langle v_1, v_2 \rangle)$ is a redex that reduces to v_1 .
- $\operatorname{snd}(\langle v_1, v_2 \rangle)$ is a redex that reduces to v_2 .
- $(\lambda x : \tau . e)(v)$ is a redex that reduces to $e[x \mapsto v]$.
- $(\Lambda \alpha . v)[\tau]$ is a redex that reduces to $v[\alpha \mapsto \tau]$.
- let x = v in e end is a redex that reduces to $e[x \mapsto v]$.
- $\mathbf{fix} f : \tau . v$ is a redex that reduces to $v[f \mapsto \mathbf{fix} f : \tau . v]$.
- case v of ms is a redex if v ↓ p ⇒ (Θ; θ) is derivable for some clause p ⇒ e in ms, and the redex reduces to e[Θ][θ]. Note that there may be certain amount of nondeterminism in the reduction of case v of ms as v may match the patterns in several clauses in ms.

Given a redex e_1 , we write $e_1 \hookrightarrow e_2$ if e_1 reduces to e_2 . If $e'_i = E[e_i]$ for i = 1, 2 and e_1 is a redex reducing to e_2 , then we write $e'_1 \hookrightarrow e'_2$ and say that e'_1 reduces to e'_2 in one step.

Let \hookrightarrow^* be the reflexive and transitive closure of \hookrightarrow . We say that e_1 reduces to e_2 (in many steps) if $e_1 \hookrightarrow^* e_2$ holds.

Given a closed well-typed expression e in $\lambda_{2,G\mu}$, we use |e| for the type erasure of e, that is, the expression obtained from erasing all types in e. We can then evaluate |e| in a untyped λ -calculus extended with pattern matching. Clearly, $e \hookrightarrow^* e'$ holds if and only if |e| evaluates to |e'|. In other words, $\lambda_{2,G\mu}$ supports type-erasure semantics.

2.5 Type Soundness

Given an expression variable context Γ such that $\Gamma(x)$ is a closed type for each $x \in \operatorname{\mathbf{dom}}(\Gamma)$, we write $\theta : \Gamma$ if $\cdot; \vdash \theta(x) : \Gamma(x)$ is derivable for each $x \in \operatorname{\mathbf{dom}}(\theta) = \operatorname{\mathbf{dom}}(\Gamma)$. In general, we write $(\Theta; \theta) : (\Delta; \Gamma)$ to mean that $\vdash \Theta$: Δ is derivable and $\theta : \Gamma[\Theta]$ holds. The following lemma essentially verifies that the rules for deriving judgments of the form $p \downarrow \tau \Rightarrow (\Delta; \Gamma)$ are properly formed.

LEMMA 2.3. Assume that $\Delta_0 \vdash p \downarrow \tau \Rightarrow (\Delta; \Gamma)$ is derivable and $\Theta_0 : \Delta_0$ holds. If v is a closed value of the type $\tau[\Theta_0]$, that is, $\cdot; \cdot \vdash v : \tau[\Theta_0]$ is derivable, and we have $v \downarrow p \Rightarrow (\Theta, \theta)$ for some Θ and θ , then $(\Theta; \theta) : (\Delta[\Theta_0]; \Gamma[\Theta_0])$ holds.

Proof By structural induction on a derivation of $\Delta_0 \vdash p \downarrow \tau \Rightarrow (\Delta; \Gamma)$

As usual, we need the following substitution lemma to establish the subject reduction theorem for $\lambda_{2,G\mu}$.

LEMMA 2.4. Assume that $\Delta; \Gamma \vdash e : \tau$ is derivable. If $\vdash (\Theta; \theta) : (\Delta; \Gamma)$ holds, then $\cdot; \cdot \vdash e[\Theta][\theta] : \tau[\Theta]$ is derivable.

Proof By structural induction on a derivation of $\Delta; \Gamma \vdash e : \tau$.

THEOREM 2.5. (Subject Reduction) Assume that $:; \vdash e : \tau$ is derivable. If $e \hookrightarrow e'$ holds, then $:; \vdash e' : \tau$ is also derivable.

Proof Assume that $e = E[e_1]$ and $e' = E[e_2]$ for some redex e_1 that reduces to e_2 . The proof follows from structural induction on E. In the case where E = [], the proof proceeds by induction on the height of a derivation of $\cdot; \cdot \vdash e : \tau$, handling various cases through the use of Lemma 2.4. For handling the typing rule **(ty-case)**, Lemma 2.3 is also needed.

However, we cannot prove that if e is a well-typed nonvalue expression then e must reduce to another well-typed expression. In the case where $e = E[e_1]$ for some $e_1 =$ **case** v of ms that is not a redex (because v does not match any pattern in ms), the evaluation of e becomes stuck. This is so far the only reason for the evaluation of an expression to become stuck. As is the case for the usual datatypes in ML, it can also be checked whether pattern matching is exhaustive with respect to types of the form $(\vec{\tau})T$ for g.r. datatype constructors T.

3. ELABORATION

We have presented an explicitly typed language $\lambda_{2,G\mu}$. Since a programmer may be quickly overwhelmed with the need for writing types in such a setting, it becomes apparent that we need to provide an external language $ML_{2,G\mu}$ together with an elaboration process from $ML_{2,G\mu}$ to $\lambda_{2,G\mu}$ that preserves dynamic semantics.

Some of the syntax for $ML_{2,G\mu}$ is presented in Figure 6 and it should be straightforward to relate the concrete syntax

patterns	p	::=	$x \mid \langle \rangle \mid \langle p_1, p_2 \rangle \mid c(p)$
clauses	ms	::=	$(p_1 \Rightarrow e_1 \mid \dots \mid p_n \Rightarrow e_n)$
expressions	e	::=	$x \mid f \mid c \mid$
			$\langle \rangle \mid \langle e_1, e_2 \rangle \mid \mathbf{fst}(e) \mid \mathbf{snd}(e) \mid$
			$\lambda x.e \mid \lambda x: \tau.e \mid e_1(e_2) \mid$
			$\mathbf{fix} \ f.v \mid \mathbf{fix} \ f:\tau.v \mid$
			case e of ms
			let $x = e_1$ in e_2 end $\mid (e : \tau)$
values	v	::=	$x \mid c \mid \langle \rangle \mid \langle v_1, v_2 \rangle \mid$
			$\lambda x.e \mid \lambda x: \tau.e$

Figure 6: Syntax for the external language $ML_{2,G\mu}$

$$\frac{\vec{\alpha} \vdash \tau : *}{\vec{\alpha} \vdash \tau \equiv \tau} \quad \frac{T \text{ is not } T'}{\vec{\alpha}, (\vec{\tau}_1)T \equiv (\vec{\tau}_2)T', \Delta \vdash \tau_1 \equiv \tau_2}$$

$$\frac{\vec{\alpha}, \Delta \vdash \tau_1 \equiv \tau_2}{\vec{\alpha}, \alpha \equiv \alpha, \Delta \vdash \tau_1 \equiv \tau_2}$$

$$\frac{\tau \text{ contains a free occurrence of } \alpha \text{ but is not } \alpha}{\vec{\alpha}, \alpha \equiv \tau, \Delta \vdash \tau_1 \equiv \tau_2}$$

$$\frac{\tau \text{ contains a free occurrence of } \alpha \text{ but is not } \alpha}{\vec{\alpha}, \alpha \equiv \tau, \Delta \vdash \tau_1 \equiv \tau_2}$$

$$\frac{\vec{\alpha}, \Delta[\alpha \mapsto \tau] \vdash \tau_1[\alpha \mapsto \tau] \equiv \tau_2[\alpha \mapsto \tau]}{\vec{\alpha}, \alpha \equiv \tau, \Delta \vdash \tau_1 \equiv \tau_2}$$

$$\vec{\alpha}, \Delta[\alpha \mapsto \tau] \vdash \tau_1[\alpha \mapsto \tau] \equiv \tau_2[\alpha \mapsto \tau]}$$

$$\vec{\alpha}, \alpha \equiv \tau, \Delta \vdash \tau_1 \equiv \tau_2$$

$$\vec{\alpha}, \Delta[\alpha \mapsto \tau] \vdash \tau_1[\alpha \mapsto \tau] \equiv \tau_2[\alpha \mapsto \tau]}$$

$$\vec{\alpha} \text{ as no free occurrences in } \tau$$

$$\vec{\alpha}, \alpha \equiv \alpha, \Delta \vdash \tau_1 \equiv \tau_2$$

$$\vec{\alpha}, \vec{\tau} \equiv \alpha, \Delta \vdash \tau_1 \equiv \tau_2$$

$$\vec{\alpha}, (\vec{\tau}_1)T \equiv (\vec{\tau}_2)T, \Delta \vdash \tau_1 \equiv \tau_2$$

$$\vec{\alpha}, \tau_1' \equiv (\vec{\alpha}_2 \mapsto \tau_2) = \tau_2$$

$$\vec{\alpha} \text{ s a fresh skolemized constant}$$

$$\vec{\alpha}, \forall \alpha_1, \tau_1' \equiv \forall \alpha_2, \tau_2' \vdash \tau_1 = \tau_2$$

Figure 7: The rules for solving type constraints

in the examples we present to that of $\mathrm{ML}_{2,G\mu}$. The types in $\mathrm{ML}_{2,G\mu}$ are the same as in $\lambda_{2,G\mu}$. The syntax for type ascription is $(e:\tau)$, which basically means the expression eis required to be of the type τ . Also, the types for bound variables in $\mathrm{ML}_{2,G\mu}$ may be omitted. Note that the language $\mathrm{ML}_{2,G\mu}$ is not a conservative extension of ML as there are strictly more programs that are typable in $\mathrm{ML}_{2,G\mu}$ than in ML.

During the elaboration of a program, type constraints of the form $\Delta \vdash \tau_1 \equiv \tau_2$ are generated. We present a set of rules for solving such type constraints in Figure 7, where we use *T* to range over all type constructors, either builtins (* and \rightarrow), user-defined g.r. datatype constructors, or skolemized constants (introduced by applying the last rule in Figure 7)

DEFINITION 3.1. Given a type τ , the size $[\tau]$ of τ is defined as follows.

$$[\alpha] = 1 \quad [(\tau_1, \dots, \tau_n)T] = 1 + [\tau_1] + \dots + [\tau_n]$$

Furthermore, given a type equality $\tau_1 \equiv \tau_2$, its size is defined as $[\tau_1] + [\tau_2]$; given a type variable context Δ , its size is the sum of the sizes of the type equalities in Δ .

Note that for each rule in Figure 7 of the following form:

$$\frac{\Delta \vdash \tau_1 \equiv \tau_2}{\Delta' \vdash \tau_1' \equiv \tau_2'}$$

we have $[\Delta] < [\Delta']$. This observation is needed to justify the soundness and the completeness of the rules for solving type constraints.

THEOREM 3.2. $\Delta \models \tau_1 \equiv \tau_2$ holds if and only if $\Delta \vdash \tau_1 \equiv \tau_2$ is derivable.

Proof Assume that $\Delta = \vec{\alpha}, \Delta'$ for some Δ' that does not begin with a type variable. The proof follows from induction on the lexicographic ordering (n_1, n_2, n_3) , where n_1 is the number of free type variables in Δ', n_2 is the number of occurrences of \forall in Δ' and n_3 is the size of Δ' .

Therefore, the rules in Figure 7 for solving type constraints are both sound and complete.

The elaboration process for $\operatorname{ML}_{2,G\mu}$ is similar to the one for DML [25, 23], following essentially the same strategy. Given Δ , Γ and e, a synthesizing judgment Δ ; $\Gamma \vdash e \uparrow \tau \Rightarrow e^*$ means that e can be elaborated into e^* with type τ such that Δ ; $\Gamma \vdash e^* : \tau$ is derivable and |e| and $|e^*|$ are operationally equivalent, where |e| and $|e^*|$ are the erasures of eand e^* , respectively. Given Δ , Γ , e and τ , a checking judgment Δ ; $\Gamma \vdash e \downarrow \tau \Rightarrow e^*$ means that e can be elaborated into e^* such that Δ ; $\Gamma \vdash e^* : \tau$ is derivable and |e| and $|e^*|$ are operationally equivalent. We have formulated a list of rules for deriving both synthesizing and checking judgments. Please refer to [24] for these rules plus other details on the issue of elaboration in $\operatorname{ML}_{2,G\mu}$.

4. APPLICATIONS

In this section, we show how g.r. datatype constructors can be used to handle some realistic and interesting examples that involve a variety of programming features. We have finished a prototype implementation that supports most of the main features in the core of ML (e.g., pattern matching, polymorphism, effects, etc.) plus g.r. datatype constructors. The implementation, written in Objective Caml, is available at [24], where we have also presented many other examples in addition to the following ones, including an implementation of queue in message-passing style, an implementation of polymorphic marshaling as is described in [16], etc.

4.1 **Polymorphic Generic Functions**

The notion of polymorphic generic functions is introduced in [8], which allows the programmer to define polymorphic functions that may behave differently on different type arguments. We use an example to show that generic functions can be readily handled through the use of g.r. datatype constructors.

In the C programming language, sprintf is a function that takes a format string and a list of arguments, and then returns a string representation of the arguments according to the format string. Let us declare the type *FORMAT* as follows.

```
typecon (type) FORMAT =
  (int -> 'a) I of 'a FORMAT
| (char -> 'a) C of 'a FORMAT
| ('a) S_ of string * 'a FORMAT
| (string) S0 of string
```

```
fun sprintf fmt = let
fun aux pre (I fmt) =
    (fn i => aux (pre ^ int2string i) fmt)
    | aux pre (C fmt) =
      (fn c => aux (pre ^ char2string c) fmt)
    | aux pre (S_ (s, fmt)) = aux (pre ^ s) fmt
    | aux pre (S0 s) = pre ^ s
    withtype string -> 'a FORMAT -> 'a
in aux "" fmt end
withtype 'a FORMAT -> 'a
```

Figure 8: An implementation of the sprintf function

When applied to a format of the type $(\tau_1 \rightarrow \ldots \rightarrow \tau_n \rightarrow \text{string})FORMAT$, the *sprintf* function expects that the *n* arguments following the format have the types τ_1, \ldots, τ_n , respectively. We give an implementation of *sprintf* in Figure 8. We can make a format expression more readable by defining an infix operator \$ for application and currying $S_{_}$ into S.

infixr \$
fun f \$ x = f (x)
fun S s fmt = S_ (s, fmt)

For instance, the following expression binds fmt with a format of the type (int \rightarrow char \rightarrow string)FORMAT.

val fmt = S "int i = " \$ I \$
 S " and char c = " \$ C \$ S0 ""

As can be expected, sprintf(fmt) returns a function of the type int \rightarrow char \rightarrow string, which yields the following string

when applied to the integer 1 and the character a.

Certainly, a functions like *sprintf* can also be implemented through the use of type classes (or their variants). The above implementation of *sprintf* is actually adopted from [15]. In this case, the format argument of the *sprintf* function is most likely to be provided by the user instead of being automatically synthesized and the very issue of overloading addressed by type classes does not really seem to exist here. Therefore, we feel the above implementation of *sprintf* through g.r. datatype constructors is more natural and direct.

4.2 Implementing Staged Computation

We outline an implementation of staged computation [7, 19] through the use of higher-order abstract syntax. We first associate a few more value constructors with the g.r. datatype constructor HOAS defined in Section 1.

typecon (type) HOAS =

```
| {'a}. ('a) HOASvar of string
| {'a}. ('a) HOASif of
        bool HOAS * 'a HOAS * 'a HOAS
```

Obviously, *HOASif* is introduced for forming h.o.a.s trees to represent conditional expressions. In general, many more language constructs can be readily handled by properly associating some value constructors with *HOAS*. The only (ad hoc and ugly) use of *HOASvar* is shown in Figure 9, where a translation from higher-order abstract syntax (h.o.a.s.) to

```
typecon FOAS =
 FOASvar of string
| {'a}. FOASlift of 'a
| FOAStup of FOAS * FOAS
| FOASlam of string * FOAS
| FOASapp of FOAS * FOAS
| FOASfix of string * FOAS
| FOASif of FOAS * FOAS * FOAS
(* 'new_name()' produces a fresh name *)
val new_name: unit -> string
fun h2f (HOASvar name) = FOASvar name
  | h2f (HOASlift v) = FOASlift v
  | h2f (HOAStup (e1,e2)) = FOAStup(h2f e1,h2f e2)
  | h2f (HOASlam f) = let
      val name = new_name ()
    in
      FOASlam (name, h2f (f (HOASvar name)))
    end
  h2f (HOASapp (e1,e2)) = FOASapp(h2f e1,h2f e2)
  | h2f (HOASfix f) = let
      val name = new_name ()
    in
      FOASfix (name, h2f (f (HOASvar name)))
   end
  | h2f (HOASif (e1, e2, e3)) =
   FOASif (h2f e1, h2f e2, h2f e3)
withtype {'a}. 'a HOAS -> FOAS
```

Figure 9: A translation from h.o.a.s to f.o.a.s

first-order abstract syntax (f.o.a.s.) is given. For instance, the translation of $HOASlam(fn \ x \Rightarrow x)$) is simply

FOASlam("x", FOASvar("x"))

(assuming "x" is the freshly generated name for the bound variable x).

Also, we assume a built-in function *compile* of the type $\forall \alpha.(\alpha) HOAS \rightarrow \alpha$ that compiles h.o.a.s. trees. For instance, *compile* can be implemented in such a manner: Given a h.o.a.s tree *e*, we translate *e* into a f.o.a.s tree h2f(e) and then compile the f.o.a.s. tree with a standard approach (as is done in Scheme). Note that the function *compile* corresponds to the function *run* in MetaML [19].

As an example, we stage the usual power function as follows, where the bloated syntax is soon to be replaced with some syntactic sugar.

```
fun power1 n =
    if n = 0 then HOASlam (fn x => HOASlift 1)
    else HOASlam (fn (x: int HOAS) =>
        HOASapp (HOASlift *,
            HOAStup (x, HOASapp (power1 (n-1), x))))
withtype int -> (int -> int) HOAS
```

Then we can define the square function as follows.

val square1: int -> int = compile (power1 2)

It can be readily verified that the f.o.a.s. tree translated from (*power1* 2) represents the following program:

(fn x2 => x2 * (fn x1 => x1 * (fn x0 => 1) x1) x2)

Now suppose we stage the power function as follows.

```
\begin{aligned} & `(xf) &= HOASlift(xf) \\ & `(c) &= HOASlift(c) \\ & `(\langle \rangle) &= HOASlift(\langle \rangle) \\ & `(\langle e_1, e_2 \rangle) &= HOASlift(\langle \rangle) \\ & `(\langle e_1, e_2, e_2) \rangle &= HOASig(`(e_1), `(e_2), `(e_3)) \\ & `(\lambda x. e) &= HOASlam(\lambda x. `(e[x \mapsto \hat{}(x)])) \\ & `(\lambda x: \tau. e) &= HOASlam(\lambda x: \langle \tau \rangle. `(e[x \mapsto \hat{}(x)])) \\ & `(e_1(e_2)) &= HOASlam(\lambda x: \langle \tau \rangle. `(e[x \mapsto \hat{}(x)])) \\ & `(e_1(e_2)) &= HOASfix(\lambda f. `(v[f \mapsto \hat{}(x)])) \\ & `(fix f. v) &= HOASfix(\lambda f. `(v[f \mapsto \hat{}(f)])) \\ & `(fix f: \tau. v) &= HOASfix(\lambda f: \langle \tau \rangle. `(v[f \mapsto \hat{}(f)])) \\ & `(e: \tau) &= (`(e): \langle \tau \rangle) \\ & `(\hat{}(e)) &= e \end{aligned}
```

Figure 10: Syntactic sugar for staged computation

fun power2 n x =
 if n = 0 then (HOASlift 1)
 else HOASapp (
 HOASlift *, HOAStup (x, power2 (n-1) x))
withtype int -> (int) HOAS -> (int) HOAS

Then the square function can be define as:

val square2: int -> int =

compile(HOASlam(fn (x: int HOAS) => power2 2 x))

This time, the f.o.a.s. tree translated from the following h.o.a.s tree

HOASlam (fn (x: int HOAS) => power2 2 x)

is (fn x => x * (x * 1)).

In Figure 10, we introduce some syntactic sugar to facilitate staged computation. Note that we now write $\langle \tau \rangle$ for $(\tau)HOAS$. Essentially, '(e) corresponds to $\langle e \rangle$ in the syntax of MetaML, and $\hat{}(e)$ corresponds to $\tilde{}(e)$. For instance, in our concrete syntax, the code '(fn (x: int) => x * x) expands into the following code, which has the type $\langle \text{int} \rightarrow \text{int} \rangle$.

```
HOASlam (fn (x: <int>) =>
HOASapp (HOASlift *, HOAStup (x, x)))
```

We reject code in which some syntactic sugar cannot be removed. For instance, $\mathbf{x} + \mathbf{1}$ is ill-formed since the symbol $\mathbf{\hat{z}}$ can not be translated away. However, '($\mathbf{x+1}$) is well-formed, which translates into:

HOASapp(HOASlift +, HOAStup(x, HOASlift 1))

Therefore, ill-formedness is context-sensitive.

The above functions *power1*, *square1*, *power2* and *square2* can now be written as follows.

fun power1 n =
 if n = 0 then '(fn x => 1)
 else '(fn x => x * ^(power1 (n-1)) x)
withtype int -> <int -> int>

val square1 = compile '(fn x => ^(power1 2) x)

fun power2 n x =
 if n = 0 then '1 else '(^x * ^(power2 (n-1) x))

```
val square2 = compile '(fn x => ^(power2 2 'x))
```

Generally speaking, we expect the following. Assume that e is an expression of type τ in MetaML. Let e^* be the expression obtained from replacing each $\langle \cdot \rangle$ in e with '(·) and

each ~ with ^ and then translating away the syntactic sugar. Then e^* should have the same type τ (if we identify the type constructor $\langle \cdot \rangle$ in MetaML with *HOAS*).

Unfortunately, the outlined implementation of staged computation contains an annoying problem, which is often called *open code extrusion*. For instance, the following program:

(fn x: int HOAS => ^(compile '(x)))

translates into the following h.o.a.s. tree t:

HOASlam (fn x: (int HOAS) HOAS => compile (x))

Suppose we want to compile t; then we need to turn t into a f.o.a.s tree by applying the function h2f to t; clearly, evaluating h2f(t) leads to a call of *compile* on *HOASvar*("x") (assuming "x" is the freshly generated name for the bound variable x); but this call leads to a run-time error as there is no way to compile a variable.

It is of great difficulty to properly address the problem with open code extrusion. For an approach to implementing staged computation that can prevent open code extrusion, please refer to [3], where a g.r. datatype constructor is formed for representing typed <u>code via deBruijn indices</u>.

In [7], a language Mini-ML_e with a type system based on the modal logic S4 is presented for studying staged computation. There, the type constructor \Box is intended to capture the closedness of code. Since h.o.a.s. trees (with no use of *HOASvar*) can only represent closed expressions, we naturally expect a relation between \Box and *HOAS*. This is to be studied in future.

4.3 Implementing Programming Objects

We briefly outline an approach to implementing objects through the use of g.r. datatype constructors. When compared with various existing approaches in the literature, this approach addresses many difficult issues in objectedoriented programming (e.g., parametric polymorphism, binary methods, the self type, etc.) in a purely type-theoretical manner, which we feel is both natural and satisfactory. In the following presentation, we take a view of objects in the spirit of Smalltalk [9, 13], suggesting to conceptualize an object as a little intelligent being that is capable of performing actions according to the messages it receives.

We assume the existence of a guarded recursive datatype constructor MSG that takes a type τ and forms a message type $(\tau)MSG$.² Also, we require that MSG be extensible (like the exception type in ML). After receiving a message of type $(\tau)MSG$, an object is expected to return a value of type τ . Therefore, we assign an object the following type OBJ:

$$OBJ = \forall \alpha.(\alpha) MSG \rightarrow \alpha$$

Suppose that we have declared through some syntax that MSGgetfst, MSGgetsnd, MSGsetfst and MSGsetsnd are message constructors of the following types, where **1** stands for the unit type.

MSGgetfst	:	(int)MSG
MSGgetsnd	:	(int)MSG
MSGsetfst	:	$int \rightarrow (1)MSC$
MSGsetsnd	:	$int \rightarrow (1)MSG$

In Figure 11, we implement integer pairs in a messagepassing style, where the withtype clause is a type annotation that assigns the type $int \rightarrow int \rightarrow OBJ$ to the defined

```
fun newIntPair x y = let
val xref = ref x and yref = ref y
fun dispatch MSGgetfst = !xref
| dispatch MSGgetsnd = !yref
| dispatch (MSGsetfst x') = (xref := x')
| dispatch (MSGsetsnd y') = (yref := y')
| dispatch msg = raise UnknownMessage
in dispatch end
withtype int -> int -> OBJ
```

Figure 11: An implementation of integer pairs

function *newIntPair*. We point out it is solely for illustration purpose that we use the prefix MSG in the name of each message constructor. Given integers x and y, we can form an integer pair anIntPair by calling newIntPair(x)(y); we can then send the message MSGgetfst to the pair to obtain its first component: anIntPair(MSGgetfst); we can also reset its first component to x' by sending the message MSGsetfst(x') to the pair: anIntPair(MSGsetfst(x')); operations on the second component of the pair can be performed similarly. Note that an exception is raised at run-time if anIntPair cannot interpret a message sent to it.

Classes Obviously, there exist some serious problems with the above approach to implementing objects. Since every object is currently assigned the type OBJ, we cannot use types to differentiate objects. For instance, suppose that MSGfoo is another declared message constructor of the type (1)MSG; then anIntPair(MSGfoo) is well-typed, but its execution leads to an uncaught exception UnknownMessage at run-time. This is clearly undesirable: anIntPair(MSGfoo)should be rejected at compile-time as an ill-typed expression. We address this problem by providing the type constructor MSG with another parameter. Given a type τ and a class C, $(\tau)MSG(C)$ is a type; the intuition is that a message of the type $(\tau)MSG(C)$ should only be sent to objects in the class C, to which we assign the type OBJ(C) defined as follows:

$$OBJ(C) = \forall \alpha.(\alpha) MSG(C) \rightarrow \alpha$$

First and foremost, we emphasize that a class is *not* a type; it is really a tag used to differentiate messages. For instance, we may declare a class *IntPairClass* and associate with it the following message constructors of the corresponding types:

MSGgetfst	:	(int)MSG(IntPairClass)
MSGgetsnd	:	(int)MSG(IntPairClass)
MSGsetfst	:	$int \rightarrow (1)MSG(IntPairClass)$
MSGsetsnd	:	$int \rightarrow (1)MSG(IntPairClass)$

The function *newIntPair* can now be given the type $\operatorname{int} \rightarrow OBJ(IntPairClass)$; since *anIntPair* has the type OBJ(IntPairClass), *anIntPair(MSGfoo)* becomes ill-typed if *MSGfoo* has a type (1)*MSG(C)* for some class *C* that is not *IntPairClass*. Following Dependent ML [25, 23], we use **class** as the sort for classes.

Parameterized Classes There is an immediate need for class tags parameterizing over types. Suppose we are to generalize the monomorphic function *newIntPair* into a polymorphic function *newPair*, which can take arguments x and y of any types and then return an object representing the pair whose first and second components are x and y, respectively. We need a class constructor *PairClass* that takes two given types τ_1 and τ_2 , to form a class $(\tau_1, \tau_2)PairClass$. We may use some syntax to declare such a class construc-

 $^{^2{\}rm In}$ the following presentation, when the arguments of a constructor are types, we always write the arguments in front of the constructor.

```
fun newPair x y = let
 val xref = ref x and yref = ref y
 fun dispatch MSGgetfst = !xref
    | dispatch MSGgetsnd = !yref
    | dispatch (MSGsetfst x') = (xref := x')
    | dispatch (MSGsetsnd y') = (yref := y')
    | dispatch msg = raise UnknownMessage
in dispatch end
withtype {'a,'b}. 'a -> 'b -> OBJ(('a,'b)PairClass)
fun newColoredPair c x y = let
 val cref = ref c
 and xref = ref x and yref = ref y
 fun dispatch MSGgetcolor = !cref
    | dispatch (MSGsetcolor c') = (cref := c')
    dispatch MSGgetfst = !xref
    | dispatch MSGgetsnd = !yref
    | dispatch (MSGsetfst x') = (xref := x')
    | dispatch (MSGsetsnd y') = (yref := y')
    | dispatch msg = raise UnknownMessage
in dispatch end
withtype {'a,'b} color ->
         'a -> 'b -> OBJ (('a, 'b)ColoredPairClass)
```

Figure 12: Functions for constructing objects in the classes *PairClass* and *ColoredPairClass*

tor and associate with it the following polymorphic message constructors:

MSGgetfst	:	$\forall \alpha. \forall \beta. (\alpha) MSG((\alpha, \beta) PairClass)$
MSGgetsnd	:	$\forall \alpha. \forall \beta. (\beta) MSG((\alpha, \beta) PairClass)$
MSGsetfst	:	$\forall \alpha. \forall \beta. \alpha \rightarrow (1) MSG((\alpha, \beta) PairClass)$
MSGsetsnd	:	$\forall \alpha. \forall \beta. \beta \to (1) MSG((\alpha, \beta) PairClass)$

The function *newPair* for constructing pair objects is implemented in Figure 12.

Subclasses Inheritance is a major issue in object-oriented programming as it can significantly facilitate code organization and reuse. We approach the issue of inheritance by introducing a predicate \leq on the sort class; given two classes C_1 and C_2 , we write $C_1 \leq C_2$ to mean that C_1 is a subclass of C_2 . The type of a message constructor mc is now of the general form $\forall \vec{\alpha}. \Pi a \triangleleft C.(\tau) MSG(a)$ or $\forall \vec{\alpha}. \Pi a \triangleleft C. \tau_1 \rightarrow (\tau_2) MSG(a)$, where $a \triangleleft C$ means that a is of the subset sort $\{a : class \mid a \leq C\}$, i.e., the sort for all subclasses of the class C; for a sequence of types $\vec{\tau}$ that is of the same length as $\vec{\alpha}$, $mc[\vec{\tau}]$ becomes a message constructor that is polymorphic on all subclasses of $C_0 = C[\vec{\alpha} \mapsto \vec{\tau}]$; therefore, mc can be used to construct a message for any object tagged by a subclass of C_0 . For instance, the types of the message constructors associated with PairClass are now listed in Figure 13. Suppose we introduce another class constructor ColoredPairClass, which takes two types to form a class, and assume the following holds, i.e., (τ_1, τ_2) Colored Pair Class is a subclass of (τ_1, τ_2) Pair Class for any types τ_1 and τ_2 :

 $\forall \alpha \forall \beta. (\alpha, \beta) Colored PairClass \leq (\alpha, \beta) PairClass$

We then associate with *ColoredPairClass* the message constructors *MSGgetcolor* and *MSGsetcolor*, whose types are given in Figure 13. Note that *color* is just some already defined type for colors.

We can then implement the function *newColoredPair* in

Figure 12 for constructing colored pairs. Clearly, the implementation of *newColoredPair* shares a lot of common code with that of *newPair*. We plan to provide some syntactic support for the programmer to effectively reuse the code in the implementation of *newPair* when implementing *newColoredPair*.

Binary Methods Our approach to typed object-oriented programming offers a clean solution to handling binary methods. For instance, we can declare a class *EqClass* and associate with it two message constructors *MSGeq* and *MSGneq* which are assigned the following types:

```
\begin{array}{rcl} MSGeq & : & \Pi a \triangleleft EqClass.OBJ(a) \rightarrow (\texttt{bool})MSG(a) \\ MSGneq & : & \Pi a \triangleleft EqClass.OBJ(a) \rightarrow (\texttt{bool})MSG(a) \end{array}
```

Suppose *self* is an object of type OBJ(C) for some $C \leq Eq$. If we pass a message MSGeq(other) to *self*, *other* is required to have the type OBJ(C) in order for *self*(MSGeq(other)) to be well-typed. Therefore, *self* and *other* must be two objects belonging to the same class.

The Self Type Our approach also offers a clean solution to handling the notion of *self type*, namely, the type for the receiver of a message. Suppose we want to support a message MSGcopy that can be sent to any object to obtain a copy of the object.³ We may assume MSGcopy is a message constructor associated with some class ObjClass and $C \leq ObjClass$ holds for any class C. We can assign MSGcopythe following type to indicate that the returned object is in the same class as the object to which the message is sent, since self(MSGcopy) has the type OBJ(C) whenever self is an object of type OBJ(C) for some class C.

MSGcopy : $\Pi a \triangleleft ObjClass.(OBJ(a))MSG(a)$

If this is done in Java, all we can state in the type system of Java is that an object is to return another object after receiving the message *MSGcopy*. This is imprecise and is a rich source for the use of type downcasting.

Inheritance Inheritance is handled in a Smalltalk-like manner, but there is some significant difference. For those who are familiar with exceptions in Standard ML, we point out that the way that method lookup is implemented resembles how exceptions are handled by exception handlers. We now use a concrete example to illustrate how inheritance can be implemented. This is also a proper place for us to introduce some syntax that is designed to facilitate OOP. We use the following syntax:

class ObjClass { MSGcopy: selfType => self; }

to declare a class tag ObjClass and a message constructor MSGcopy of the type:

$$\Pi a \triangleleft ObjClass.(OBJ(a))MSG(a)$$

Note **selfType** is merely syntactic sugar here. In addition, the syntax also *automatically* induces the definition of a function *superObj*, which is written as follows in ML-like syntax.

```
(* self is just an ordinary variable *)
fun superObj self = let
  fun dispatch MSGcopy = self
        | dispatch msg = raise UnknownMessage
in dispatch end
withtype {a <: ObjClass} OBJ(a) -> OBJ(a)
```

 $^{^{3}\}mathrm{It}$ is up to the actual implementation as to how such a copy can be constructed.

```
\begin{array}{lll} MSGgetfst & : & \forall \alpha.\forall \beta.\Pi a \lhd (\alpha, \beta) PairClass.(\alpha) MSG(a) \\ MSGgetsnd & : & \forall \alpha.\forall \beta.\Pi a \lhd (\alpha, \beta) PairClass.(\beta) MSG(a) \\ MSGsetfst & : & \forall \alpha.\forall \beta.\Pi a \lhd (\alpha, \beta) PairClass.\alpha \rightarrow (\mathbf{1}) MSG(a) \\ MSGsetsnd & : & \forall \alpha.\forall \beta.\Pi a \lhd (\alpha, \beta) PairClass.\beta \rightarrow (\mathbf{1}) MSG(a) \\ MSGgetcolor & : & \forall \alpha\forall \beta.\Pi a \lhd (\alpha, \beta) Colored PairClass.(color) MSGgetcolor(a) \\ MSGsetcolor & : & \forall \alpha\forall \beta.\Pi a \lhd (\alpha, \beta) Colored PairClass.color \rightarrow (\mathbf{1}) MSGsetcolor(a) \\ \end{array}
```

Figure 13: Some message constructors and their types

The function superObj we present here is solely for explaining how inheritance can be implemented; such a function is not to occur in a source program. The type of the function $\Pi a \triangleleft ObjClass.OBJ(a) \rightarrow OBJ(a)$ indicates this is a function that takes an object tagged by a subclass C of ObjClass and returns an object tagged by the same class. In general, for each class C, a "super" function of the type $\Pi a \triangleleft C.OBJ(a) \rightarrow OBJ(a)$ is associated with C. It should soon be clear that such a function holds the key to implementing inheritance. Now we use the following syntax to declare classes Int1Class and ColoredInt1Class as well as some message constructors associated with them.

```
class Int1Class inherits ObjClass {
    MSGget_x: int;
    MSGset_x (int): unit;
    MSGdouble: unit =>
        self(MSGset_x(2 * self(MSGget_x));
}
class ColoredInt1Class inherits Int1Class {
    (* color is just some already defined type *)
    MSGget_c: color;
    MSGset_c (color): unit;
}
```

The "super" functions associated with the classes *Int1Class* and *ColoredInt1Class* are automatically induced as follows.

```
fun superInt1 self = let
  fun dispatch MSGdouble =
      self(MSGset_x(2 * self(MSGget_x)))
      | dispatch msg = superObj self msg
in dispatch end
withtype {a <: Int1Class} OBJ(a) -> OBJ(a)
fun superColoredInt1 self = let
  fun dispatch msg = superInt1 self msg
in dispatch end
withtype {a <: ColoredInt1Class} OBJ(a) -> OBJ(a)
```

The functions for constructing objects in the classes Int1Class and ColoredInt1Class are implemented in Figure 14. There is something really interesting here. Suppose we use newInt1 and newColoredInt1 to construct objects o_1 and o_2 that are tagged with Int1Class and ColoredInt1Class, respectively. If we send the message MSGcopy to o_1 , then a copy of o_1 (not o_1 itself) is returned. If we send MSGdouble to o_2 , then the integer value of o_2 is doubled as it inherits the corresponding method from the class Int1Class. What is remarkable is that the object o_2 itself is returned if we send the message MSGcopy to o_2 . The reason is that no copying method is defined for o_2 ; searching for a copying method, o_2 eventually finds the one defined in the class ObjClass(as there is no such a method defined in either the class ColoredInt1Class or the class Int1Class). This is a desirable consequence: if o_2 were treated as an object in the class Int1Class, the returned object would be in the class

```
fun newInt1 (x0: int) = let
  val x = ref x0
  fun dispatch MSGget_x = !x
    | dispatch (MSGset_x x') = (x := x')
    | dispatch MSGcopy = newInt1 (!x)
    | dispatch msg = superInt1 dispatch msg
in dispatch end
withtype int -> OBJ(Int1Class)
fun newColoredInt1 (c0: color, x0: int) = let
  val c = ref c0 and x = ref x0
  fun dispatch MSGget_c = !c
    | dispatch (MSGset_c c') = (c := c')
    dispatch MSGget_x = !x
    | dispatch (MSGset_x x') = (x := x')
    | dispatch msg = superColoredInt1 dispatch msg
in dispatch end
withtype int -> OBJ(ColoredInt1Class)
```

Figure 14: Functions for constructing objects in *Int1Class* and *ColoredInt1Class*

Int1Class, not in the class ColoredInt1Class, as it would be generated by $newInt1(o_2(MSGget_x))$, making the type system unsound. We are currently not aware of any other approach to correctly typing this simple example. Note that the function newInt becomes ill-typed if we employ the notion MyType here.

Subtypes There is not an explicit subtyping relation in our approach. Instead, we can use existentially quantified dependent types to simulate subtyping. For instance, given a class tag C, the type $OBJECT(C) = \Sigma a \triangleleft C.OBJ(a)$ is the sum of all types OBJ(a) satisfying $a \leq C$. Hence, for each $C_1 \leq C$, $OBJ(C_1)$ can be regarded as a subtype of OBJECT(C) as each value of the type $OBJ(C_1)$ can be coerced into a value of the type OBJECT(C). As an example, the type

OBJ((OBJECT(Int1Class), OBJECT(Int1Class))PairClass)

is for pair objects whose both components are objects in some subclasses of Int1Class.

5. RELATED WORK AND CONCLUSION

Our work is related to both intentional polymorphism and type classes.

There have already been a rich body of studies in the literature on passing types at run-time in a type-safe manner [6, 5, 21]. Many of such studies follow the framework in [10], which essentially provides a construct typecase at term level to perform type analysis and a primitive recursor Typerec over type names at type level to define new type

constructors. However, in the presence of **Typerec**, it becomes rather difficult to define a proper equality on types. For instance, the type equality defined in [10] is not closed under substitution. The language λ_i^{ML} in [10] is subsequently extended to

The language λ_i^{ML} in [10] is subsequently extended to λ_R in [6] to support type-erasure semantics. The type constructor R in λ_R can be seen as a special g.r. datatype constructor.

The system of type classes in Haskell provides a programming methodology that is of great use in practice. A common approach to implementing type classes is through dictionary-passing, where a dictionary is essentially a record of the member functions for a particular instance of a type class [1]. We encountered the notion of g.r. datatype constructors when seeking an alternative implementation of type classes through intensional polymorphism. An approach to implementing type classes through the use of g.r. datatype constructors can be found at [24].

The dependent datatypes in DML [25, 23] also shed some light on g.r. datatype constructors. For instance, we can have the following dependent datatype declaration in DML.

```
datatype 'a list with nat =
  nil(0) | {n:nat} cons(n+1) of 'a * 'a list(n)
```

The syntax introduces a type constructor *list* that takes a type and a type index of sort *nat* to form a list type. The constructors *nil* and *cons* are assigned the following types.

$$nil : \forall \alpha.(\alpha) list(0) cons : \forall \alpha.\alpha * (\alpha) list(n) \to (\alpha) list(n+1)$$

Given a type τ and natural number n, the type $(\tau)list(n)$ is for lists with length n in which each element has the type τ . Formally, the type constructor *list* can be defined as follows:

$$\lambda \alpha.\mu t.\lambda a: nat. \exists \{0 = a\}. \mathbf{1} + \exists \{a': nat, a' + 1 = a\}. \alpha * t(a')$$

Clearly, this is also a form of guarded datatype constructor, where the guards are constraints on type index expressions (rather than on types).

Although we initially met the notion of g.r. datatype constructors during a study on run-time type-passing, we have since found a variety applications of this notion beyond type-passing (e.g., implementing staged computation and implementing programming objects). Currently, we are particularly interested in implementing a CLOS-like object system on the top of DML extended with g.r. datatype constructors, facilitating object-oriented programming styles in a typed functional programming setting.

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